

# Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 13 —

[http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563\\_spring\\_2018/](http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/)

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$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

$$-f(A) + 2f(C) + f(B) \quad -f(A) + f(C) + f(B) \quad -f(A \cap B)$$



# Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.
- Read chapter 2 from Fujishige's book.
- Read chapter 3 from Fujishige's book.
- Read chapter 4 from Fujishige's book.



# Announcements, Assignments, and Reminders

- Next homework is posted on canvas. Due Thursday 5/10, 11:59pm.
- As always, if you have any questions about anything, please ask them via our discussion board ([https://canvas.uw.edu/courses/1216339/discussion\\_topics](https://canvas.uw.edu/courses/1216339/discussion_topics)). Can meet at odd hours via zoom (send message on canvas to schedule time to chat).

# Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions,
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9): More Examples/Properties/ Other Submodular Defs., Independence,
- L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar Matroids
- L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
- L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
- L9(4/23): Polyhedra, Matroid Polytopes, Matroids  $\rightarrow$  Polymatroids
- L10(4/29): Matroids  $\rightarrow$  Polymatroids, Polymatroids, Polymatroids and Greedy,
- L11(4/30): Polymatroids, Polymatroids and Greedy
- L12(5/2): Polymatroids and Greedy, Extreme Points, Cardinality Constrained Maximization
- L13(5/7): Constrained Submodular Maximization
- L14(5/9):
- L15(5/14):
- L16(5/16):
- L17(5/21):
- L18(5/23):
- L-(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

Last day of instruction, June 1st. Finals Week: June 2-8, 2018.



# Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function  $f : 2^V \rightarrow R$  (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
- If  $f(\emptyset) \neq 0$ , can set  $f'(A) = f(A) - f(\emptyset)$  without destroying submodularity. This does not change any minima, (i.e.,  $\operatorname{argmin}_A f(A) = \operatorname{argmin}_{A'} f'(A)$ ) so we often assume all functions are normalized  $f(\emptyset) = 0$ .
- We can define several polytopes:

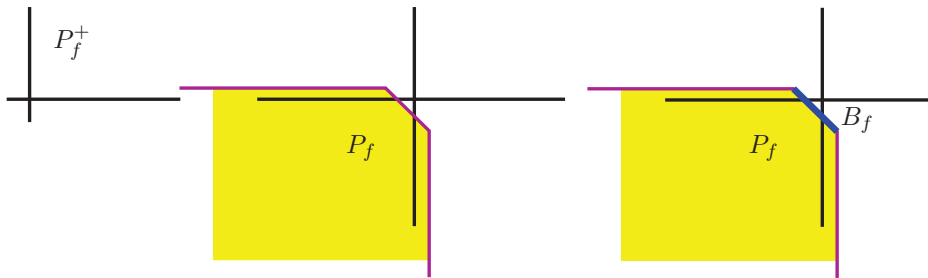
$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\} \quad (13.1)$$

$$P_f^+ = P_f \cap \{x \in \mathbb{R}^E : x \geq 0\} \quad (13.2)$$

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\} \quad (13.3)$$

- $P_f$  is what is sometimes called the extended polytope (sometimes notated as  $EP_f$ ).
- $P_f^+$  is  $P_f$  restricted to the positive orthant.
- $B_f$  is called the **base polytope**, analogous to the base in matroid.

# Multiple Polytopes in 2D associated with $f$



$$P_f^+ = P_f \cap \{x \in \mathbb{R}^E : x \geq 0\} \quad (13.1)$$

$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\} \quad (13.2)$$

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\} \quad (13.3)$$

# A polymatroid function's polyhedron is a polymatroid.

## Theorem 13.2.1

Let  $f$  be a submodular function defined on subsets of  $E$ . For any  $x \in \mathbb{R}^E$ , we have:

$$\text{rank}(x) = \max (y(E) : y \leq x, y \in P_f) = \min (x(A) + f(E \setminus A) : A \subseteq E) \quad (13.1)$$

Essentially the same theorem as Theorem ??, but note  $P_f$  rather than  $P_f^+$ . Taking  $x = 0$  we get:

## Corollary 13.2.2

Let  $f$  be a submodular function defined on subsets of  $E$ . We have:

$$\text{rank}(0) = \max (y(E) : y \leq 0, y \in P_f) = \min (f(A) : A \subseteq E) \quad (13.2)$$

# Polymatroid extreme points

## Theorem 13.2.1

For a given ordering  $E = (e_1, \dots, e_m)$  of  $E$  and a given  $E_i = (e_1, \dots, e_i)$  and  $x$  generated by  $E_i$  using the greedy procedure ( $x(e_i) = f(e_i | E_{i-1})$ ), then  $x$  is an extreme point of  $P_f$  when  $f$  is submodular.

## Proof.

- We already saw that  $x \in P_f$  (Theorem ??).
- To show that  $x$  is an extreme point of  $P_f$ , note that it is the unique solution of the following system of equations

$$x(E_j) = f(E_j) \text{ for } 1 \leq j \leq i \leq m \quad (13.4)$$

$$x(e) = 0 \text{ for } e \in E \setminus E_i \quad (13.5)$$

There are  $i \leq m$  equations and  $i \leq m$  unknowns, and simple Gaussian elimination gives us back the  $x$  constructed via the Greedy algorithm!!

# Polymatroid extreme points

- Moreover, we have (and will ultimately prove)

## Corollary 13.2.2

*If  $x$  is an extreme point of  $P_f$  and  $B \subseteq E$  is given such that  $\text{supp}(x) = \{e \in E : x(e) \neq 0\} \subseteq B \subseteq \cup(A : x(A) = f(A)) = \text{sat}(x)$ , then  $x$  is generated using greedy by some ordering of  $B$ .*

- Note,  $\text{sat}(x) = \text{cl}(x) = \cup(A : x(A) = f(A))$  is also called **the closure** of  $x$  (recall that sets  $A$  such that  $x(A) = f(A)$  are called tight, and such sets are closed under union and intersection, as seen in Lecture 10, Theorem ??)
- Thus,  $\text{cl}(x)$  is a tight set.
- Also,  $\text{supp}(x) = \{e \in E : x(e) \neq 0\}$  is called the support of  $x$ .
- For arbitrary  $x$ ,  $\text{supp}(x)$  is not necessarily tight, but for an extreme point,  $\text{supp}(x)$  is.

# Polymatroid with labeled edge lengths

- Recall

$$f(e|A) = f(A+e) - f(A)$$

- Notice how

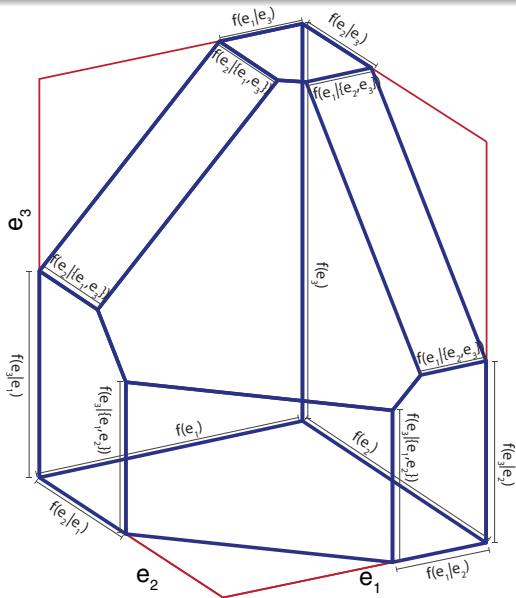
submodularity,

$f(e|B) \leq f(e|A)$  for  $A \subseteq B$ , defines the shape of the polytope.

- In fact, we have strictness here

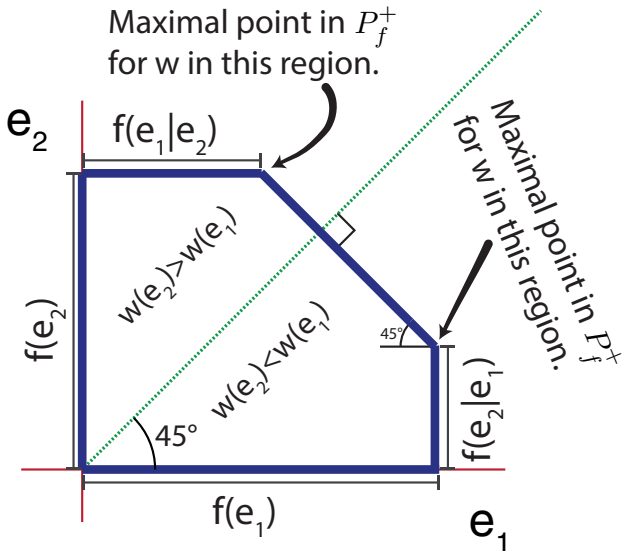
$f(e|B) < f(e|A)$  for  $A \subset B$ .

- Also, consider how the greedy algorithm proceeds along the edges of the polytope.



# Intuition: why greedy works with polymatroids

- Given  $w$ , the goal is to find  $x = (x(e_1), x(e_2))$  that maximizes  $x^\top w = x(e_1)w(e_1) + x(e_2)w(e_2)$ .
- If  $w(e_2) > w(e_1)$  the upper extreme point indicated maximizes  $x^\top w$  over  $x \in P_f^+$ .
- If  $w(e_2) < w(e_1)$  the lower extreme point indicated maximizes  $x^\top w$  over  $x \in P_f^+$ .



# The Greedy Algorithm for Submodular Max

A bit more precisely:

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## Algorithm 1: The Greedy Algorithm

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1 Set  $S_0 \leftarrow \emptyset$  ;
2 for  $i \leftarrow 0 \dots |E| - 1$  do
3   Choose  $v_i$  as follows:
4    $v_i \in \operatorname{argmax}_{v \in V \setminus S_i} f(\{v\} | S_i) = \operatorname{argmax}_{v \in V \setminus S_i} f(S_i \cup \{v\})$  ;
5   Set  $S_{i+1} \leftarrow S_i \cup \{v_i\}$  ;

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# Greedy Algorithm for Card. Constrained Submodular Max

- This algorithm has a guarantee

## Theorem 13.2.1

*Given a polymatroid function  $f$ , the above greedy algorithm returns sets  $S_i$  such that for each  $i$  we have  $f(S_i) \geq (1 - 1/e) \max_{|S| \leq i} f(S)$ .*

- To approximately find  $A^* \in \operatorname{argmax} \{f(A) : |A| \leq k\}$ , we repeat the greedy step until  $k = i + 1$ :
- Again, since this generalizes max  $k$ -cover, Feige (1998) showed that this can't be improved. Unless  $P = NP$ , no polynomial time algorithm can do better than  $(1 - 1/e + \epsilon)$  for any  $\epsilon > 0$ .

# The Greedy Algorithm: $1 - 1/e$ intuition.

- At step  $i < k$ , greedy chooses  $v_i$  to maximize  $f(v|S_i)$ .

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$$\exists v \in V \setminus S_i : f(v|S_i) = f(S_i + v|S_i) \geq \frac{1}{k}(\text{OPT} - f(S_i)) \quad (13.1)$$

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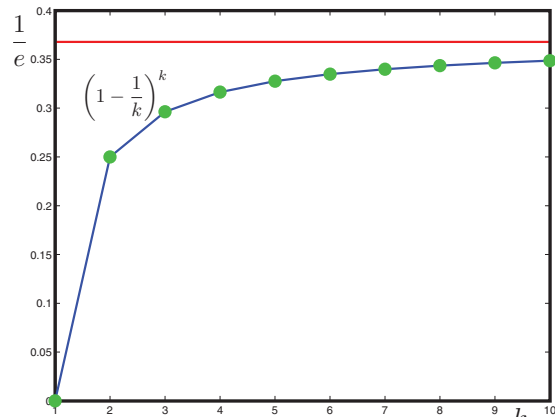
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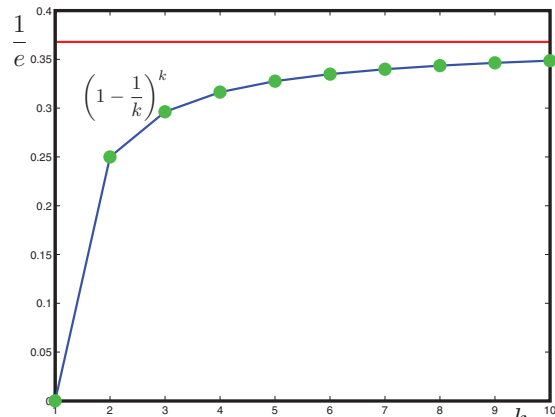
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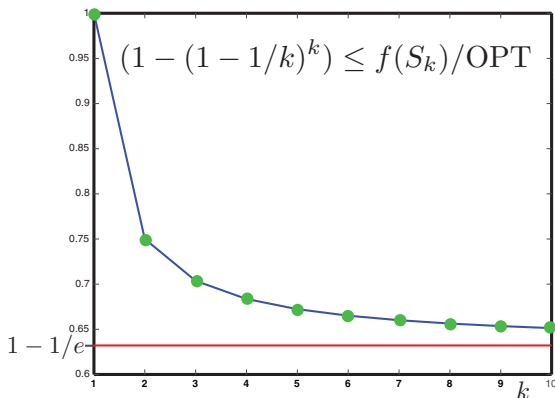
Equation (13.10) will show that Equation (13.1)  $\Rightarrow$ :

$$\begin{aligned} \text{OPT} - f(S_{i+1}) &\leq (1 - 1/k)(\text{OPT} - f(S_i)) \\ \Rightarrow \text{OPT} - f(S_k) &\leq (1 - 1/k)^k \text{OPT} \\ &\leq 1/e \text{OPT} \\ \Rightarrow \text{OPT}(1 - 1/e) &\leq f(S_k) \end{aligned}$$

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Equation (13.10) will show that Equation (13.1)  $\Rightarrow$ :

$$\begin{aligned} & \text{OPT} - f(S_{i+1}) \\ & \leq (1 - 1/k)(\text{OPT} - f(S_i)) \\ \Rightarrow & \text{OPT} - f(S_k) \\ & \leq (1 - 1/k)^k \text{OPT} \\ & \leq 1/e \text{OPT} \\ \Rightarrow & \text{OPT}(1 - 1/e) \leq f(S_k) \end{aligned}$$



# Cardinality Constrained Polymatroid Max Theorem

## Theorem 13.3.1 (Nemhauser et al. 1978)

Given non-negative monotone submodular function  $f : 2^V \rightarrow \mathbb{R}_+$ , define  $\{S_i\}_{i \geq 0}$  to be the chain formed by the greedy algorithm (Eqn. (??)). Then for all  $k, \ell \in \mathbb{Z}_{++}$ , we have:

$$f(S_\ell) \geq (1 - e^{-\ell/k}) \max_{S:|S| \leq k} f(S) \quad (13.2)$$

and in particular, for  $\ell = k$ , we have  $f(S_k) \geq (1 - 1/e) \max_{S:|S| \leq k} f(S)$ .

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- $\ell$  is size of set we are choosing (i.e., we choose  $S_\ell$  from greedy chain).
- Bound is how well does  $S_\ell$  (of size  $\ell$ ) do relative to  $S^*$ , the optimal set of size  $k$ .

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- $\ell$  is size of set we are choosing (i.e., we choose  $S_\ell$  from greedy chain).
- Bound is how well does  $S_\ell$  (of size  $\ell$ ) do relative to  $S^*$ , the optimal set of size  $k$ .
- Intuitively, bound should get worse when  $\ell < k$  and get better when  $\ell > k$ .

# Cardinality Constrained Polymatroid Max Theorem

## Proof of Theorem 13.3.1.

...

# Cardinality Constrained Polymatroid Max Theorem

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- Fix  $\ell$  (number of items greedy will chose) and  $k$  (size of optimal set to compare against).

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## Proof of Theorem 13.3.1.

- Fix  $\ell$  (number of items greedy will chose) and  $k$  (size of optimal set to compare against).
- Set  $S^* \in \operatorname{argmax} \{f(S) : |S| \leq k\}$

...



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- Order  $S^* = (v_1^*, v_2^*, \dots, v_k^*)$  arbitrarily.

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- w.l.o.g. assume  $|S^*| = k$ .
- Order  $S^* = (v_1^*, v_2^*, \dots, v_k^*)$  arbitrarily.
- Let  $S_i = (v_1, v_2, \dots, v_i)$  be the greedy order chain chosen by the algorithm, for  $i \in \{1, 2, \dots, \ell\}$ .

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- Let  $S_i = (v_1, v_2, \dots, v_i)$  be the greedy order chain chosen by the algorithm, for  $i \in \{1, 2, \dots, \ell\}$ .
- Then the following inequalities (on the next slide) follow:

...

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

...

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

- For all  $i < \ell$ , we have

$$f(S^*)$$

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

- For all  $i < \ell$ , we have

$$f(S^*) \leq f(S^* \cup S_i)$$

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

- For all  $i < \ell$ , we have

$$f(S^*) \leq f(S^* \cup S_i) = f(S_i) + f(S^* | S_i) \quad (13.3)$$

...



# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

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$$= f(S_i) + \sum_{j=1}^k f(v_j^* | S_i \cup \{v_1^*, v_2^*, \dots, v_{j-1}^*\}) \quad (13.4)$$

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$$\leq f(S_i) + \sum_{v \in S^*} f(v_{i+1} | S_i)$$

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$$\leq f(S_i) + \sum_{v \in S^*} f(v | S_i) \quad (13.5)$$

$$\leq f(S_i) + \sum_{v \in S^*} f(v_{i+1} | S_i) = f(S_i) + \sum_{v \in S^*} f(S_{i+1} | S_i) \quad (13.6)$$

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# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

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$$= f(S_i) + \sum_{j=1}^k f(v_j^* | S_i \cup \{v_1^*, v_2^*, \dots, v_{j-1}^*\}) \quad (13.4)$$

$$\leq f(S_i) + \sum_{v \in S^*} f(v | S_i) \quad (13.5)$$

$$\leq f(S_i) + \sum_{v \in S^*} f(v_{i+1} | S_i) = f(S_i) + \sum_{v \in S^*} f(S_{i+1} | S_i) \quad (13.6)$$

$$= f(S_i) + k f(S_{i+1} | S_i) \quad (13.7)$$

...

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

- For all  $i < \ell$ , we have

$$f(S^*) \leq f(S^* \cup S_i) = f(S_i) + f(S^*|S_i) \quad (13.3)$$

$$= f(S_i) + \sum_{j=1}^k f(v_j^*|S_i \cup \{v_1^*, v_2^*, \dots, v_{j-1}^*\}) \quad (13.4)$$

$$\leq f(S_i) + \sum_{v \in S^*} f(v|S_i) \quad (13.5)$$

$$\leq f(S_i) + \sum_{v \in S^*} f(v_{i+1}|S_i) = f(S_i) + \sum_{v \in S^*} f(S_{i+1}|S_i) \quad (13.6)$$

$$= f(S_i) + kf(S_{i+1}|S_i) \quad (13.7)$$

- Therefore, we have Equation 13.1, i.e.,:

$$f(S^*) - f(S_i) \leq kf(S_{i+1}|S_i) = k(f(S_{i+1}) - f(S_i)) \quad (13.8)$$

...

# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

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- Define gap  $\delta_i \triangleq f(S^*) - f(S_i)$ , so  $\delta_i - \delta_{i+1} = f(S_{i+1}) - f(S_i)$ ,



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$$\delta_i \leq k(\delta_i - \delta_{i+1}) \tag{13.9}$$

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- The relationship between  $\delta_0$  and  $\delta_\ell$  is then

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- Now,  $\delta_0 = f(S^*) - f(\emptyset) \leq f(S^*)$  since  $f \geq 0$ .
- Also, by variational bound  $1 - x \leq e^{-x}$  for  $x \in \mathbb{R}$ , we have

$$\delta_\ell \leq \left(1 - \frac{1}{k}\right)^\ell \delta_0 \leq e^{-\ell/k} f(S^*) \quad (13.12)$$

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... proof of Theorem 13.3.1 cont.



# Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 13.3.1 cont.

- When we identify  $\delta_i = f(S^*) - f(S_\ell)$ , a bit of rearranging then gives:

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- With  $\ell = k$ , when picking  $k$  items, greedy gets  $(1 - 1/e) \approx 0.6321$  bound. This means that if  $S_k$  is greedy solution of size  $k$ , and  $S^*$  is an optimal solution of size  $k$ ,  $f(S_k) \geq (1 - 1/e)f(S^*) \approx 0.6321f(S^*)$ .



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- So solution, in the worst case, quickly gets very good. Typical/practical case is much better.

# Greedy running time

- Greedy computes a new maximum  $n = |V|$  times, and each maximum computation requires  $O(n)$  comparisons, leading to  $O(n^2)$  computation for greedy.

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- This is called Minoux's 1977 Accelerated Greedy strategy (and has been rediscovered a few times, e.g., "Lazy greedy"), and runs much faster while still producing same answer.
- We describe it next:

# Minoux's Accelerated Greedy for Submodular Functions

- At stage  $i$  in the algorithm, we have a set of gains  $f(v|S_i)$  for all  $v \notin S_i$ . Store these values  $\alpha_v \leftarrow f(v|S_i)$  in sorted priority queue.

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- For  $v \notin S_{i+1}$  we have  $f(v|S_{i+1}) \leq f(v|S_i)$  by submodularity.
- Therefore, if we find a  $v'$  such that  $f(v'|S_{i+1}) \geq \alpha_v$  for all  $v \neq v'$ , then since

$$f(v'|S_{i+1}) \geq \alpha_v = f(v|S_i) \geq f(v|S_{i+1}) \quad (13.14)$$

we have the true max, and we need not re-evaluate gains of other elements again.

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- Strategy is: find the  $\operatorname{argmax}_{v' \in V \setminus S_{i+1}} \alpha_{v'}$ , and then compute the real  $f(v'|S_{i+1})$ . If it is greater than all other  $\alpha_v$ 's then that's the next greedy step. Otherwise, replace  $\alpha_{v'}$  with its real value, resort ( $O(\log n)$ ), and repeat.

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- Minoux's algorithm is exact, in that it has the same guarantees as does the standard  $O(n^2)$  greedy algorithm (will return the same answers, i.e., those having the  $1 - 1/e$  guarantee).



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- Algorithm has been rediscovered (I think) independently (CELF - cost-effective lazy forward selection, Leskovec et al., 2007)
- Can be used used for "big data" sets (e.g., social networks, selecting blogs of greatest influence, document summarization, etc.).

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- If a popped item is fresh, it must be the maximum — this can happen if, at given iteration,  $v$  was first popped and neither fresh nor maximum so placed back in the queue, and it then percolates back to the top at which point it is fresh — thereby avoid extra queue check.

# Minoux's Accelerated Greedy Algorithm Submodular Max

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## Algorithm 2: Minoux's Accelerated Greedy Algorithm

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```

1 Set  $S_0 \leftarrow \emptyset$  ;  $i \leftarrow 0$  ; Initialize priority queue  $Q$  ;
2 for  $v \in E$  do
3   INSERT( $Q, f(v)$ )
4 repeat
5    $(v, \alpha) \leftarrow \text{pop}(Q)$  ;
6   if  $\alpha$  not "fresh" then
7     recompute  $\alpha \leftarrow f(v|S_i)$ 
8   if (popped  $\alpha$  in line 5 was "fresh") OR ( $\alpha \geq \max(Q)$ ) then
9     Set  $S_{i+1} \leftarrow S_i \cup \{v\}$  ;
10     $i \leftarrow i + 1$  ;
11  else
12    insert( $Q, (v, \alpha)$ )
13 until  $i = |E|$  ;

```

---

# (Minimum) Submodular Set Cover

- Given polymatroid  $f$ , goal is to find a covering set of minimum cost:

$$S^* \in \operatorname{argmin}_{S \subseteq V} |S| \text{ such that } f(S) \geq \alpha \quad (13.18)$$

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- Normally take  $\alpha = f(V)$  but defining  $f'(A) = \min \{f(A), \alpha\}$  we can take any  $\alpha$ . Hence, we have equivalent formulation:

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- Note that this immediately generalizes standard set cover, in which case  $f(A)$  is the cardinality of the union of sets indexed by  $A$ .
- Greedy Algorithm: Pick the first chain item  $S_i$  chosen by aforementioned greedy algorithm such that  $f(S_i) \geq \alpha$  and output that as solution.

# (Minimum) Submodular Set Cover: Approximation Analysis

- For integer valued  $f$ , this greedy algorithm an  $O(\log(\max_{s \in V} f(\{s\})))$  approximation. Let  $S^*$  be optimal, and  $S^G$  be greedy solution, then

$$|S^G| \leq |S^*| H(\max_{s \in V} f(\{s\})) = |S^*| O(\log_e(\max_{s \in V} f(\{s\}))) \quad (13.20)$$

where  $H$  is the harmonic function, i.e.,  $H(d) = \sum_{i=1}^d (1/i)$ .



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where  $S_T$  is the final greedy solution that occurs at step  $T$ .

# (Minimum) Submodular Set Cover: Approximation Analysis

- For integer valued  $f$ , this greedy algorithm an  $O(\log(\max_{s \in V} f(\{s\})))$  approximation. Let  $S^*$  be optimal, and  $S^G$  be greedy solution, then

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- Set cover is hard to approximate with a factor better than  $(1 - \epsilon) \log \alpha$ , where  $\alpha$  is the desired cover constraint.

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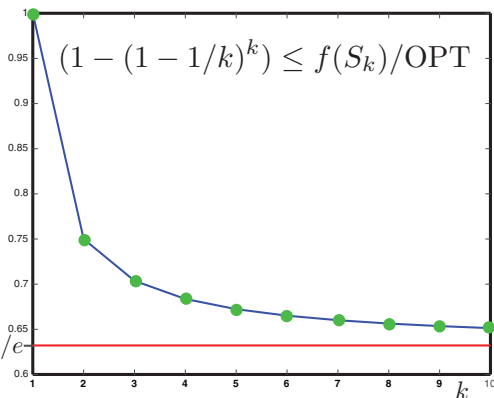
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- Minoux's accelerated greedy trick.



# The Greedy Algorithm: $1 - 1/e$ intuition.

- At step  $i < k$ , greedy chooses  $v_i$  to maximize  $f(v|S_i)$ .
- Let  $S^*$  be optimal solution (of size  $k$ ) and  $\text{OPT} = f(S^*)$ . By submodularity, we will show:

$$\exists v \in V \setminus S_i : f(v|S_i) = f(S_i + v|S_i) \geq \frac{1}{k}(\text{OPT} - f(S_i)) \quad (13.1)$$



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$$E[f(a_{i+1}|A_i)] \geq \frac{f(OPT) - f(A_i)}{k} \quad (13.22)$$

where  $A_i = (a_1, a_2, \dots, a_i)$  are the first  $i$  elements chosen by the strategy.

# Curvature of a Submodular function

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$$f(A + v) - f(A) \geq (1 - c')f(v) \quad (13.24)$$

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- Matroid rank functions with some dependence is maximally curved.

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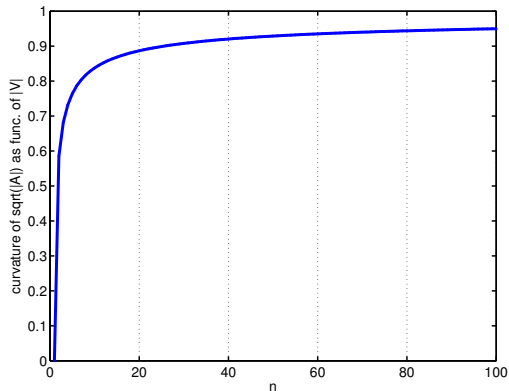
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- It will be remembered the notion of “partial dependence” within polymatroid functions.

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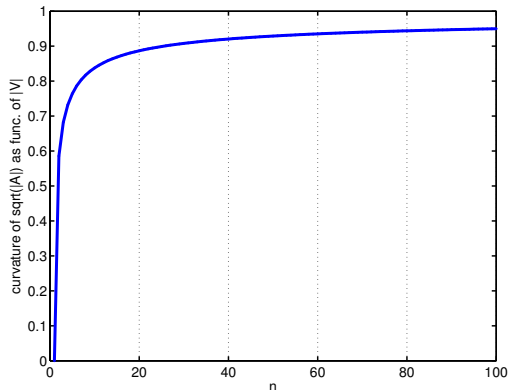


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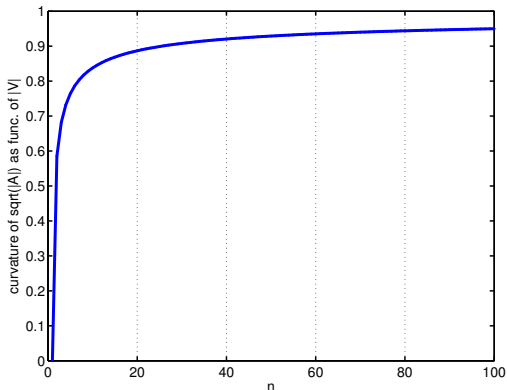
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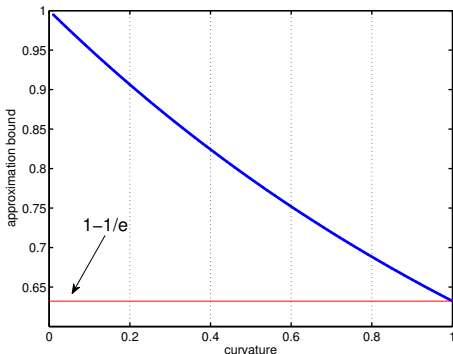
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- For  $k$ -uniform matroid (i.e.,  $k$ -cardinality constraints), then approximation factor becomes  $\frac{1}{c}(1 - e^{-c})$



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- For purely supermodular optimization (i.e.,  $\kappa_f = 0$ ) we get that greedy has a guarantee of  $1 - \kappa_g$ .

# Generalizations

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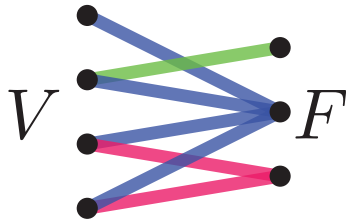
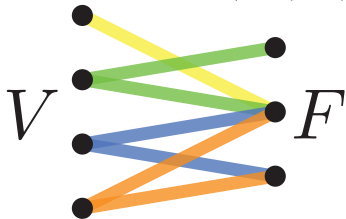


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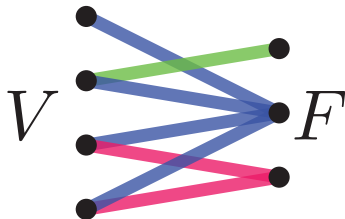
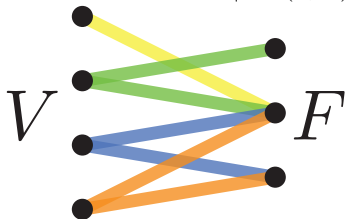
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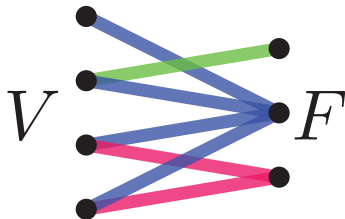
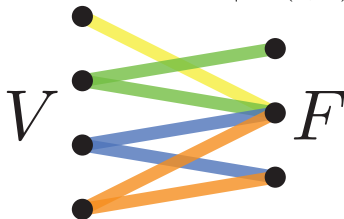
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- In bipartite graph case, therefore, can be solved in polynomial time.

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- Then a Hamiltonian cycle exists iff there is an  $n$ -element intersection of  $M_1$ ,  $M_2$ , and  $M_3$ .

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- But bipartite graph example gives us hope for 2 matroids, as in that case we can easily solve  $\max |X|$  s.t.  $x \in \mathcal{I}_1 \cap \mathcal{I}_2$ .

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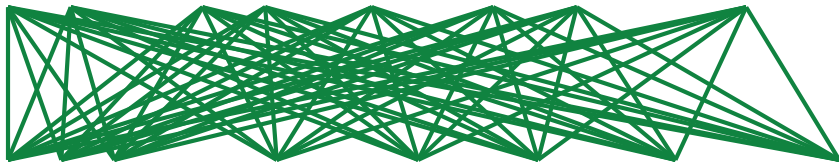
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- $E$  corresponds to, say, an English language sentence and  $F$  corresponds to a French language sentence — goal is to form a matching (an alignment) between the two.

# Greedy over $> 1$ matroids: Multiple Language Alignment

- Consider English string and French string, set up as a bipartite graph.

I have ... as an example of public ownership



je le ai ... comme exemple de propriété publique

# Greedy over $> 1$ matroids: Multiple Language Alignment

- One possible alignment, a matching, with score as sum of edge weights.

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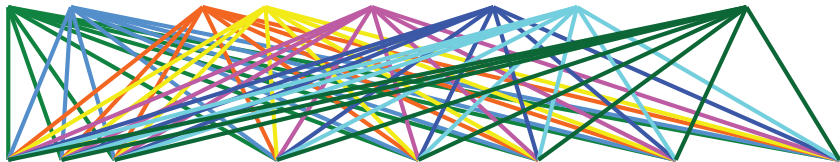
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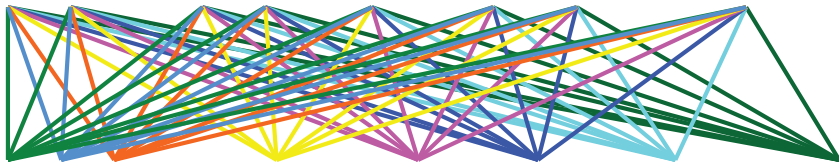
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- Maximizing submodular function subject to multiple matroid constraints addresses this problem.

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- We can solve this via submodular maximization subject to multiple matroid independence constraints as we next describe ...

# Submodular Welfare: Submodular Max over matroid partition

- Create new ground set  $E'$  as disjoint union of  $n$  copies of the ground set. I.e.,

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- Submodular welfare maximization becomes matroid constrained submodular max  $\max \{f'(S) : S \in \mathcal{I}\}$ , so greedy algorithm gives a  $1/2$  approximation.

# Submodular Social Welfare






- Have  $n = 6$  people (who don't like to share) and  $|E| = m = 7$  pieces of sushi. E.g.,  $e \in E$  might be "salmon roll".



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





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


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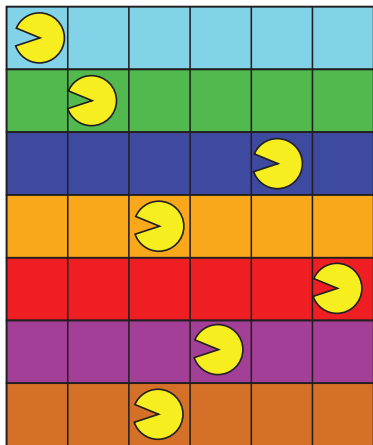
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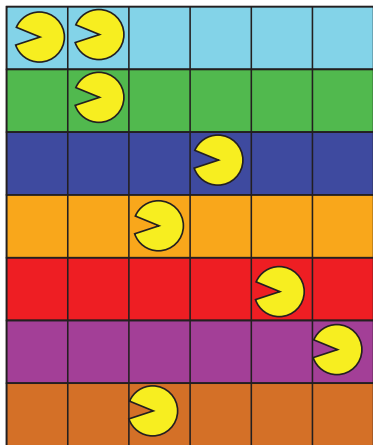
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- Important: A knapsack constraint yields an independence system (down closed) but it is not a matroid!
- $c(e)$  may be seen as the cost of item  $e$  and if  $c(e) = 1$  for all  $e$ , then we recover the cardinality constraint we saw earlier.

# Monotone Submodular over Knapsack Constraint

- Greedy can be seen as choosing the best **gain**: Starting with  $S_0 = \emptyset$ , we repeat the following greedy step

$$S_{i+1} = S_i \cup \left\{ \operatorname{argmax}_{v \in V \setminus S_i} \left( f(S_i \cup \{v\}) - f(S_i) \right) \right\} \quad (13.30)$$

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- Core idea in knapsack case: Greedy can be extended to choose next whatever looks **cost-normalized** best, i.e., Starting some initial set  $S_0$ , we repeat the following cost-normalized greedy step

$$S_{i+1} = S_i \cup \left\{ \operatorname{argmax}_{v \in V \setminus S_i} \frac{f(S_i \cup \{v\}) - f(S_i)}{c(v)} \right\} \quad (13.31)$$

which we repeat until  $c(S_{i+1}) > b$  and then take  $S_i$  as the solution.

# A Knapsack Constraint

- There are a number of ways of getting approximation bounds using this strategy.
- If we run the normalized greedy procedure starting with  $S_0 = \emptyset$ , and compare the solution found with the max of the singletons  $\max_{v \in V} f(\{v\})$ , choosing the max, then we get a  $(1 - e^{-1/2}) \approx 0.39$  approximation, in  $O(n^2)$  time (Minoux trick also possible for further speed)
- Partial enumeration: On the other hand, we can get a  $(1 - e^{-1}) \approx 0.63$  approximation in  $O(n^5)$  time if we run the above procedure starting from all sets of cardinality three (so restart for all  $S_0$  such that  $|S_0| = 3$ ), and compare that with the best singleton and pairwise solution.
- Extending something similar to this to  $d$  simultaneous knapsack constraints is possible as well.

# Local Search Algorithms

From J. Vondrak

- Local search involves switching up to  $t$  elements, as long as it provides a (non-trivial) improvement; can iterate in several phases. Some examples follow:
- $1/3$  approximation to unconstrained non-monotone maximization [Feige, Mirrokni, Vondrak, 2007]
- $1/(k + 2 + \frac{1}{k} + \delta_t)$  approximation for non-monotone maximization subject to  $k$  matroids [Lee, Mirrokni, Nagarajan, Sviridenko, 2009]
- $1/(k + \delta_t)$  approximation for monotone submodular maximization subject to  $k \geq 2$  matroids [Lee, Sviridenko, Vondrak, 2010].

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- Thus, any approximation algorithm must be for unipolar submodular functions. E.g., non-negative but otherwise arbitrary submodular functions.
- We may get a  $(\frac{1}{3} - \frac{\epsilon}{n})$  approximation for maximizing non-monotone non-negative submodular functions, with most  $O(\frac{1}{\epsilon} n^3 \log n)$  function calls using approximate local maxima.

# Submodularity and local optima

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- Similarly, given  $v_1, v_2 \notin S$ , and  $f(S + v_1) \leq f(S)$  and  $f(S + v_2) \leq f(S)$ . Submodularity requires  $f(S + v_1) + f(S + v_2) \geq f(S) + f(S + v_1 + v_2)$  which requires  $f(S + v_1 + v_2) \leq f(S)$ .



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- Finding a local maximum is already hard (PLS-complete), but it is possible to find an approximate local maximum relatively efficiently.

# Submodularity and local optima

- Given any submodular function  $f$ , a set  $S \subseteq V$  is a local maximum of  $f$  if  $f(S - v) \leq f(S)$  for all  $v \in S$  and  $f(S + v) \leq f(S)$  for all  $v \in V \setminus S$  (i.e., local in a Hamming ball of radius 1).
- The following interesting result is true for any submodular function:

## Lemma 13.6.1

*Given a submodular function  $f$ , if  $S$  is a local maximum of  $f$ , and  $I \subseteq S$  or  $I \supseteq S$ , then  $f(I) \leq f(S)$ .*

- In other words, once we have identified a local maximum, the two intervals in the Boolean lattice  $[\emptyset, S]$  and  $[S, V]$  can be ruled out as a possible improvement over  $S$ .
- Finding a local maximum is already hard (PLS-complete), but it is possible to find an approximate local maximum relatively efficiently.
- This is the approach that yields the  $(\frac{1}{3} - \frac{\epsilon}{n})$  approximation algorithm.

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## Algorithm 6: Randomized Linear-time non-monotone submodular max

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- 1 Set  $L \leftarrow \emptyset$  ;  $U \leftarrow V$  /\* Lower  $L$ , upper  $U$ . Invariant:  $L \subseteq U$  \*/ ;
  - 2 Order elements of  $V = (v_1, v_2, \dots, v_n)$  arbitrarily ;
  - 3 **for**  $i \leftarrow 0 \dots |V|$  **do**
  - 4      $a \leftarrow [f(v_i|L)]_+$ ;  $b \leftarrow [-f(U|U \setminus \{v_i\})]_+$  ;
  - 5     **if**  $a = b = 0$  **then**  $p \leftarrow 1/2$  ;
  - 6     ;
  - 7     **else**  $p \leftarrow a/(a + b)$ ;
  - 8     ;
  - 9     **if** Flip of coin with  $\Pr(\text{heads}) = p$  draws heads **then**
  - 10          $L \leftarrow L \cup \{v_i\}$  ;
  - 11     **Otherwise** /\* if the coin drew tails, an event with prob.  $1 - p$  \*/
  - 12          $U \leftarrow U \setminus \{v\}$
  - 13 **return**  $L$  (which is the same as  $U$  at this point)
-

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- In practice, run it multiple times, each with a different random permutation of the elements, and then take the cumulative best.
- It may be possible to choose the random order smartly to get better results in practice.

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- Often the computational costs of the algorithms are prohibitive (e.g., exponential in  $k$ ) with large constants, so these algorithms might not scale.
- On the other hand, these algorithms offer deep and interesting intuition into submodular functions, beyond what we have covered here.



# Some results on submodular maximization

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- We can recover  $1 - 1/e$  approximation using the continuous greedy algorithm on the multilinear extension and then using pipage rounding to re-integerize the solution (see J. Vondrak's publications).
- More general constraints are possible too, as we see on the next table (for references, see Jan Vondrak's publications <http://theory.stanford.edu/~jvondrak/>).

# Submodular Max Summary - 2012: From J. Vondrak

## Monotone Maximization

Constraint	Approximation	Hardness	Technique
$ S  \leq k$	$1 - 1/e$	$1 - 1/e$	greedy
matroid	$1 - 1/e$	$1 - 1/e$	multilinear ext.
$O(1)$ knapsacks	$1 - 1/e$	$1 - 1/e$	multilinear ext.
$k$ matroids	$k + \epsilon$	$k / \log k$	local search
$k$ matroids and $O(1)$ knapsacks	$O(k)$	$k / \log k$	multilinear ext.

## Nonmonotone Maximization

Constraint	Approximation	Hardness	Technique
Unconstrained	$1/2$	$1/2$	combinatorial
matroid	$1/e$	0.48	multilinear ext.
$O(1)$ knapsacks	$1/e$	0.49	multilinear ext.
$k$ matroids	$k + O(1)$	$k / \log k$	local search
$k$ matroids and $O(1)$ knapsacks	$O(k)$	$k / \log k$	multilinear ext.