

Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 14 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

$= f(A) + 2f(C) + f(B) \quad = f(A) + f(C) + f(B) \quad = f(A \cap B)$



Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.
- Read chapter 2 from Fujishige's book.
- Read chapter 3 from Fujishige's book.
- Read chapter 4 from Fujishige's book.

Announcements, Assignments, and Reminders

- Next homework is posted on canvas. Due Thursday 5/10, 11:59pm.
- As always, if you have any questions about anything, please ask then via our discussion board (https://canvas.uw.edu/courses/1216339/discussion_topics). Can meet at odd hours via zoom (send message on canvas to schedule time to chat).

Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions,
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9): More Examples/Properties/ Other Submodular Defs., Independence,
- L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar Matroids
- L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
- L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
- L9(4/23): Polyhedra, Matroid Polytopes, Matroids \rightarrow Polymatroids
- L10(4/29): Matroids \rightarrow Polymatroids, Polymatroids, Polymatroids and Greedy,
- L11(4/30): Polymatroids, Polymatroids and Greedy
- L12(5/2): Polymatroids and Greedy, Extreme Points, Cardinality Constrained Maximization
- L13(5/7): Constrained Submodular Maximization
- L14(5/9): Submodular Max w. Other Constraints, Cont. Extensions, Lovasz Extension
- L15(5/14):
- L16(5/16):
- L17(5/21):
- L18(5/23):
- L-(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

Last day of instruction, June 1st. Finals Week: June 2-8, 2018.

Priority Queue

- Use a priority queue Q as a data structure: operations include:

- Insert an item (v, α) into queue, with $v \in V$ and $\alpha \in \mathbb{R}$.

$$\text{insert}(Q, (v, \alpha)) \quad (14.14)$$

- Pop the item (v, α) with maximum value α off the queue.

$$(v, \alpha) \leftarrow \text{pop}(Q) \quad (14.15)$$

- Query the value of the max item in the queue

$$\text{max}(Q) \in \mathbb{R} \quad (14.16)$$

- On next slide, we call a popped item “fresh” if the value (v, α) popped has the correct value $\alpha = f(v|S_i)$. Use extra “bit” to store this info
- If a popped item is fresh, it must be the maximum — this can happen if, at given iteration, v was first popped and neither fresh nor maximum so placed back in the queue, and it then percolates back to the top at which point it is fresh — thereby avoid extra queue check.

Minoux's Accelerated Greedy Algorithm Submodular Max

Algorithm 1: Minoux's Accelerated Greedy Algorithm

```

1 Set  $S_0 \leftarrow \emptyset$ ;  $i \leftarrow 0$ ; Initialize priority queue  $Q$ ;
2 for  $v \in E$  do
3   INSERT( $Q, f(v)$ )
4 repeat
5    $(v, \alpha) \leftarrow \text{pop}(Q)$ ;
6   if  $\alpha$  not “fresh” then
7     recompute  $\alpha \leftarrow f(v|S_i)$ 
8   if (popped  $\alpha$  in line 5 was “fresh”) OR ( $\alpha \geq \text{max}(Q)$ ) then
9     Set  $S_{i+1} \leftarrow S_i \cup \{v\}$ ;
10     $i \leftarrow i + 1$ ;
11  else
12    insert( $Q, (v, \alpha)$ )
13 until  $i = |E|$ ;

```

(Minimum) Submodular Set Cover

- Given polymatroid f , goal is to find a covering set of minimum cost:

$$S^* \in \operatorname{argmin}_{S \subseteq V} |S| \text{ such that } f(S) \geq \alpha \quad (14.14)$$

where α is a “cover” requirement.

- Normally take $\alpha = f(V)$ but defining $f'(A) = \min \{f(A), \alpha\}$ we can take any α . Hence, we have equivalent formulation:

$$S^* \in \operatorname{argmin}_{S \subseteq V} |S| \text{ such that } f'(S) \geq f'(V) \quad (14.15)$$

- Note that this immediately generalizes standard set cover, in which case $f(A)$ is the cardinality of the union of sets indexed by A .
- Greedy Algorithm: Pick the first chain item S_i chosen by aforementioned greedy algorithm such that $f(S_i) \geq \alpha$ and output that as solution.

(Minimum) Submodular Set Cover: Approximation Analysis

- For integer valued f , this greedy algorithm an $O(\log(\max_{s \in V} f(\{s\})))$ approximation. Let S^* be optimal, and S^G be greedy solution, then

$$|S^G| \leq |S^*| H(\max_{s \in V} f(\{s\})) = |S^*| O(\log_e(\max_{s \in V} f(\{s\}))) \quad (14.14)$$

where H is the harmonic function, i.e., $H(d) = \sum_{i=1}^d (1/i)$.

- If f is not integral value, then bounds we get are of the form:

$$|S^G| \leq |S^*| \left(1 + \log_e \frac{f(V)}{f(V) - f(S_{T-1})} \right) \quad (14.15)$$

where S_T is the final greedy solution that occurs at step T .

- Set cover is hard to approximate with a factor better than $(1 - \epsilon) \log \alpha$, where α is the desired cover constraint.

Curvature of a Submodular function

- By submodularity, total curvature can be computed in either form:

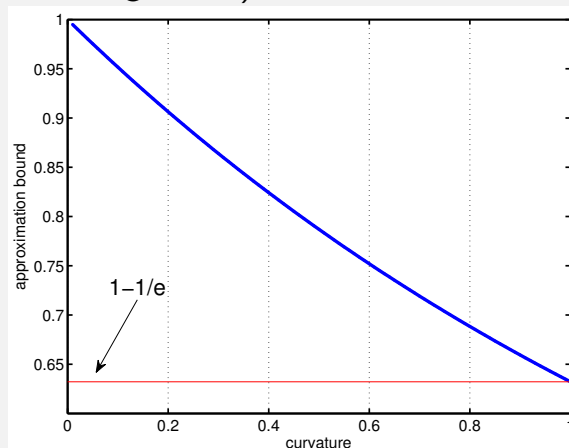
$$c \triangleq 1 - \min_{S, j \notin S: f(j|\emptyset) \neq 0} \frac{f(j|S)}{f(j|\emptyset)} = 1 - \min_{j: f(j|\emptyset) \neq 0} \frac{f(j|V \setminus \{j\})}{f(j|\emptyset)} \quad (14.18)$$

- Note: Matroid rank is either modular $c = 0$ or maximally curved $c = 1$ — hence, matroid rank can have only the extreme points of curvature, namely 0 or 1.
- Polymatroid functions are, in this sense, more nuanced, in that they allow non-extreme curvature, with $c \in [0, 1]$.
- It will be remembered the notion of “partial dependence” within polymatroid functions.

Curvature and approximation

- Curvature limitation can help the greedy algorithm in terms of approximation bounds.
- Conforti & Cornuéjols showed that greedy gives a $1/(1+c)$ approximation to $\max \{f(S) : S \in \mathcal{I}\}$ when f has total curvature c .
- Hence, greedy subject to matroid constraint is a $\max(1/(1+c), 1/2)$ approximation algorithm, and if $c < 1$ then it is better than $1/2$ (e.g., with $c = 1/4$ then we have a 0.8 algorithm).

- For k -uniform matroid (i.e., k -cardinality constraints), then approximation factor becomes $\frac{1}{c}(1 - e^{-c})$



Generalizations

- Consider a k -uniform matroid $\mathcal{M} = (V, \mathcal{I})$ where $\mathcal{I} = \{S \subseteq V : |S| \leq k\}$, and consider problem $\max \{f(A) : A \in \mathcal{I}\}$
- Hence, the greedy algorithm is $1 - 1/e$ optimal for maximizing polymatroidal f subject to a k -uniform matroid constraint.
- Might be useful to allow an arbitrary matroid (e.g., partition matroid $\mathcal{I} = \{X \subseteq V : |X \cap V_i| \leq k_i \text{ for all } i = 1, \dots, \ell\}$, or a transversal, etc).
- Knapsack constraint: if each item $v \in V$ has a cost $c(v)$, we may ask for $c(S) \leq b$ where b is a budget, in units of costs. Q: Is $\mathcal{I} = \{I : c(I) \leq b\}$ the independent sets of a matroid?
- We may wish to maximize f subject to multiple matroid constraints. I.e., $S \in \mathcal{I}_1, S \in \mathcal{I}_2, \dots, S \in \mathcal{I}_p$ where \mathcal{I}_i are independent sets of the i^{th} matroid.
- Combinations of the above (e.g., knapsack & multiple matroid constraints).

Greedy over multiple matroids

- Obvious heuristic is to use the greedy step but always stay feasible.
- I.e., Starting with $S_0 = \emptyset$, we repeat the following greedy step

$$S_{i+1} = S_i \cup \left\{ \underset{v \in V \setminus S_i : S_i + v \in \bigcap_{i=1}^p \mathcal{I}_i}{\operatorname{argmax}} f(S_i \cup \{v\}) \right\} \quad (14.1)$$

- That is, we keep choosing next whatever feasible element looks best.
- This algorithm is simple and also has a guarantee

Theorem 14.3.1

Given a polymatroid function f , and set of matroids $\{M_j = (E, \mathcal{I}_j)\}_{j=1}^p$, the above greedy algorithm returns sets S_i such that for each i we have $f(S_i) \geq \frac{1}{p+1} \max_{|S| \leq i, S \in \bigcap_{i=1}^p \mathcal{I}_i} f(S)$, assuming such sets exist.

- For one matroid, we have a $1/2$ approximation.
- Very easy algorithm, Minoux trick still possible, while addresses multiple matroid constraints — but the bound is not that good when there are many matroids.

Matroid Intersection and Bipartite Matching

- Why might we want to do matroid intersection?
- Consider bipartite graph $G = (V, F, E)$. Define two partition matroids $M_V = (E, \mathcal{I}_V)$, and $M_F = (E, \mathcal{I}_F)$.
- Independence in each matroid corresponds to:
 - 1 $I \in \mathcal{I}_V$ if $|I \cap (V, f)| \leq 1$ for all $f \in F$,
 - 2 and $I \in \mathcal{I}_F$ if $|I \cap (v, F)| \leq 1$ for all $v \in V$.



- Therefore, a matching in G is simultaneously independent in both M_V and M_F and finding the maximum matching is finding the maximum cardinality set independent in both matroids.
- In bipartite graph case, therefore, can be solved in polynomial time.

Matroid Intersection and Network Communication

- Let $G_1 = (V_1, E)$ and $G_2 = (V_2, E)$ be two graphs on an isomorphic set of edges (lets just give them same names E).
- Consider two cycle matroids associated with these graphs $M_1 = (E, \mathcal{I}_1)$ and $M_2 = (E, \mathcal{I}_2)$. They might be very different (e.g., an edge might be between two distinct nodes in G_1 but the same edge is a loop in multi-graph G_2 .)
- We may wish to find the maximum size edge-induced subgraph that is still forest in **both** graphs (i.e., adding any edges will create a circuit in either M_1 , M_2 , or both).
- This is again a matroid intersection problem.

Matroid Intersection and TSP

- Definition: a **Hamiltonian cycle** is a cycle that passes through each node exactly once.
- Given directed graph G , goal is to find such a Hamiltonian cycle.
- From G with n nodes, create G' with $n + 1$ nodes by duplicating (w.l.o.g.) a particular node $v_1 \in V(G)$ to v_1^+, v_1^- , and have all outgoing edges from v_1 come instead from v_1^- and all edges incoming to v_1 go instead to v_1^+ .
- Let M_1 be the cycle matroid on G' .
- Let M_2 be the partition matroid having as independent sets those that have no more than one edge leaving any node — i.e., $I \in \mathcal{I}(M_2)$ if $|I \cap \delta^-(v)| \leq 1$ for all $v \in V(G')$.
- Let M_3 be the partition matroid having as independent sets those that have no more than one edge entering any node — i.e., $I \in \mathcal{I}(M_3)$ if $|I \cap \delta^+(v)| \leq 1$ for all $v \in V(G')$.
- Then a Hamiltonian cycle exists iff there is an n -element intersection of M_1 , M_2 , and M_3 .

- Recall, the **traveling salesperson problem (TSP)** is the problem to, given a directed graph, start at a node, visit all cities, and return to the starting point. Optimization version does this tour at minimum cost.
- Since TSP is NP-complete, we obviously can't solve matroid

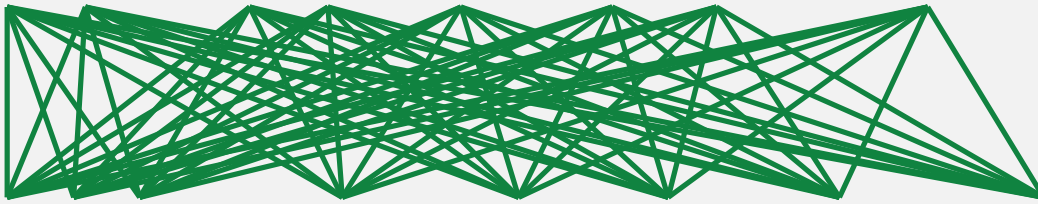
Greedy over multiple matroids: Generalized Bipartite Matching

- Generalized bipartite matching (i.e., max bipartite matching with submodular costs on the edges). Use two partition matroids (as mentioned earlier in class)
- Useful in natural language processing: Ex. Computer language translation, find an alignment between two language strings.
- Consider bipartite graph $G = (E, F, V)$ where E and F are the left/right set of nodes, respectively, and V is the set of edges.
- E corresponds to, say, an English language sentence and F corresponds to a French language sentence — goal is to form a matching (an alignment) between the two.

Greedy over > 1 matroids: Multiple Language Alignment

- Consider English string and French string, set up as a bipartite graph.

I have ... as an example of public ownership

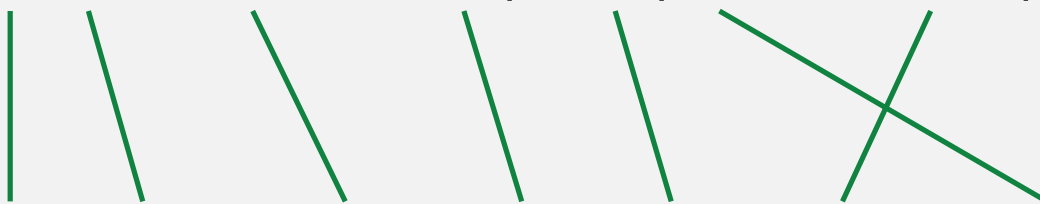


je le ai ... comme exemple de propriété publique

Greedy over > 1 matroids: Multiple Language Alignment

- One possible alignment, a matching, with score as sum of edge weights.

I have ... as an example of public ownership

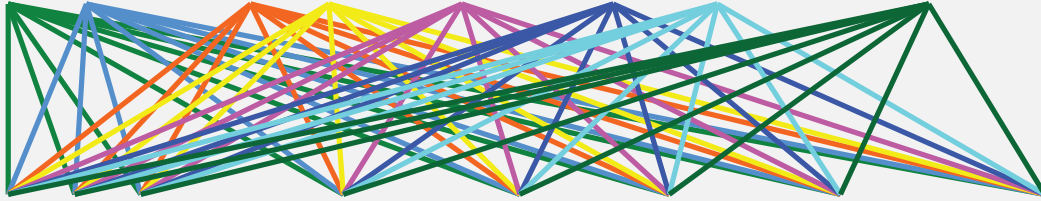


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Greedy over > 1 matroids: Multiple Language Alignment

- Edges incident to English words constitute an edge partition

I have ... as an example of public ownership



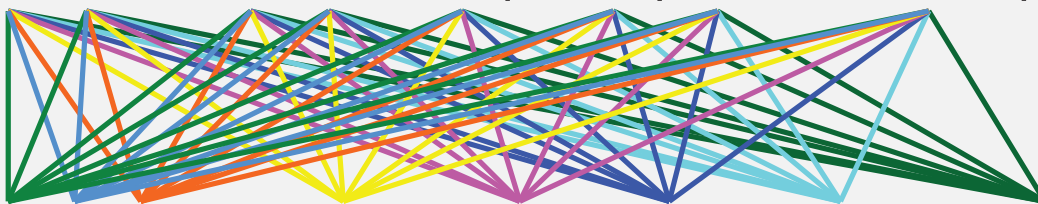
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- The two edge partitions can be used to set up two 1-partition matroids on the edges.
- For each matroid, a set of edges is independent only if the set intersects each partition block no more than one time.

Greedy over > 1 matroids: Multiple Language Alignment

- Edges incident to French words constitute an edge partition

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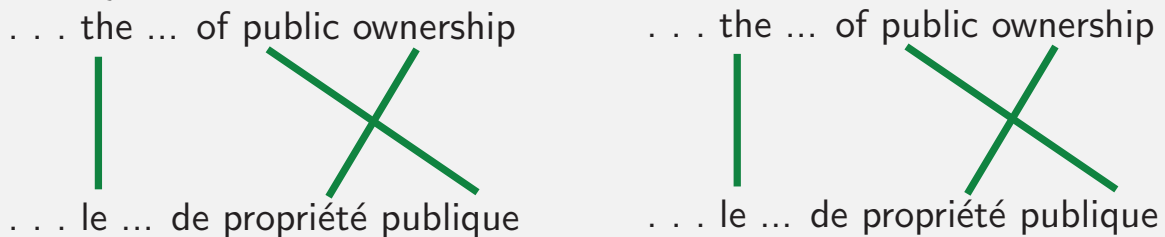
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Greedy over > 1 matroids: Multiple Language Alignment

- Typical to use bipartite matching to find an alignment between the two language strings.
- As we saw, this is equivalent to two 1-partition matroids and a non-negative modular cost function on the edges.
- We can generalize this using a polymatroid cost function on the edges, and two k -partition matroids, allowing for “fertility” in the models:

Fertility at most 1



Greedy over > 1 matroids: Multiple Language Alignment

- Typical to use bipartite matching to find an alignment between the two language strings.
- As we saw, this is equivalent to two 1-partition matroids and a non-negative modular cost function on the edges.
- We can generalize this using a polymatroid cost function on the edges, and two k -partition matroids, allowing for “fertility” in the models:

Fertility at most 2



Greedy over > 1 matroids: Multiple Language Alignment

- Generalizing further, each block of edges in each partition matroid can have its own “fertility” limit:
 $\mathcal{I} = \{X \subseteq V : |X \cap V_i| \leq k_i \text{ for all } i = 1, \dots, \ell\}.$
- Maximizing submodular function subject to multiple matroid constraints addresses this problem.

Greedy over multiple matroids: Submodular Welfare

- Submodular Welfare Maximization: Consider E a set of m goods to be distributed/partitioned among n people (“players”).
- Each player has a submodular “valuation” function, $g_i : 2^E \rightarrow \mathbb{R}_+$ that measures how “desirable” or “valuable” a given subset $A \subseteq E$ of goods are to that player.
- Assumption: No good can be shared between multiple players, each good must be allocated to a single player.
- Goal of submodular welfare: Partition the goods $E = E_1 \cup E_2 \cup \dots \cup E_n$ into n blocks in order to maximize the submodular social welfare, measured as:

$$\text{submodular-social-welfare}(E_1, E_2, \dots, E_n) = \sum_{i=1}^n g_i(E_i). \quad (14.2)$$

- We can solve this via submodular maximization subject to multiple matroid independence constraints as we next describe . . .

Submodular Welfare: Submodular Max over matroid partition

- Create new ground set E' as disjoint union of n copies of the ground set. I.e.,

$$E' = \underbrace{E \uplus E \uplus \dots \uplus E}_{n \times} \quad (14.3)$$

- Let $E^{(i)} \subset E'$ be the i^{th} block of E' .
- For any $e \in E$, the corresponding element in $E^{(i)}$ is called $(e, i) \in E^{(i)}$ (each original element is tagged by integer).
- For $e \in E$, define $E_e = \{(e', i) \in E' : e' = e\}$.
- Hence, $\{E_e\}_{e \in E}$ is a partition of E' , each block of the partition for one of the original elements in E .
- Create a 1-partition matroid $\mathcal{M} = (E', \mathcal{I})$ where

$$\mathcal{I} = \{S \subseteq E' : \forall e \in E, |S \cap E_e| \leq 1\} \quad (14.4)$$

Submodular Welfare: Submodular Max over matroid partition

- Hence, S is independent in matroid $\mathcal{M} = (E', \mathcal{I})$ if S uses each original element no more than once.
- Create submodular function $f' : 2^{E'} \rightarrow \mathbb{R}_+$ with $f'(S) = \sum_{i=1}^n g_i(S \cap E^{(i)})$.
- Submodular welfare maximization becomes matroid constrained submodular max $\max \{f'(S) : S \in \mathcal{I}\}$, so greedy algorithm gives a $1/2$ approximation.

Submodular Social Welfare










- Have $n = 6$ people (who don't like to share) and $|E| = m = 7$ pieces of sushi. E.g., $e \in E$ might be $e = \text{"salmon roll"}$.
- Goal: distribute sushi to people to maximize social welfare.
- Ground set disjoint union $E \uplus E \uplus E \uplus E \uplus E \uplus E$.
- Partition matroid partitions: $E_{e_1} \cup E_{e_2} \cup E_{e_3} \cup E_{e_4} \cup E_{e_5} \cup E_{e_6} \cup E_{e_7}$.
- independent allocation
- non-independent allocation

Submodular Social Welfare



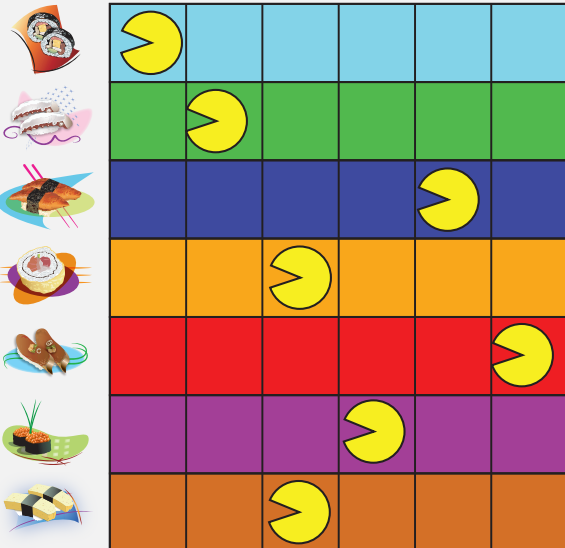
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Submodular Social Welfare



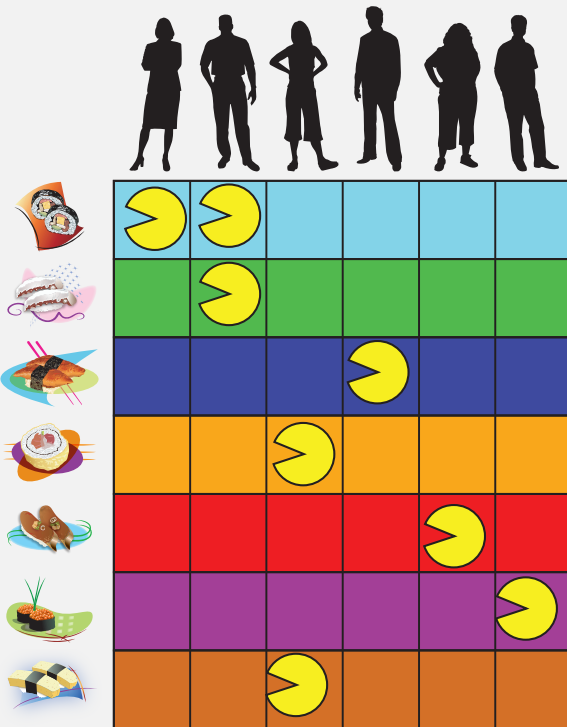
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Monotone Submodular over Knapsack Constraint

- The constraint $|A| \leq k$ is a simple cardinality constraint.
- Consider a non-negative integral modular function $c : E \rightarrow \mathbb{Z}_+$.
- A knapsack constraint would be of the form $c(A) \leq b$ where b is some integer budget that must not be exceeded. That is $\max \{f(A) : A \subseteq V, c(A) \leq b\}$.
- Important: A knapsack constraint yields an independence system (down closed) but it is not a matroid!
- $c(e)$ may be seen as the cost of item e and if $c(e) = 1$ for all e , then we recover the cardinality constraint we saw earlier.

Monotone Submodular over Knapsack Constraint

- Greedy can be seen as choosing the best **gain**: Starting with $S_0 = \emptyset$, we repeat the following greedy step

$$S_{i+1} = S_i \cup \left\{ \operatorname{argmax}_{v \in V \setminus S_i} \left(f(S_i \cup \{v\}) - f(S_i) \right) \right\} \quad (14.5)$$

the gain is $f(\{v\}|S_i) = f(S_i + v) - f(S_i)$, so greedy just chooses next the currently unselected element with greatest gain.

- Core idea in knapsack case: Greedy can be extended to choose next whatever looks **cost-normalized** best, i.e., Starting some initial set S_0 , we repeat the following cost-normalized greedy step

$$S_{i+1} = S_i \cup \left\{ \operatorname{argmax}_{v \in V \setminus S_i} \frac{f(S_i \cup \{v\}) - f(S_i)}{c(v)} \right\} \quad (14.6)$$

which we repeat until $c(S_{i+1}) > b$ and then take S_i as the solution.

A Knapsack Constraint

- There are a number of ways of getting approximation bounds using this strategy.
- If we run the normalized greedy procedure starting with $S_0 = \emptyset$, and compare the solution found with the max of the singletons $\max_{v \in V} f(\{v\})$, choosing the max, then we get a $(1 - e^{-1/2}) \approx 0.39$ approximation, in $O(n^2)$ time (Minoux trick also possible for further speed)
- Partial enumeration: On the other hand, we can get a $(1 - e^{-1}) \approx 0.63$ approximation in $O(n^5)$ time if we run the above procedure starting from all sets of cardinality three (so restart for all S_0 such that $|S_0| = 3$), and compare that with the best singleton and pairwise solution.
- Extending something similar to this to d simultaneous knapsack constraints is possible as well.

Local Search Algorithms

From J. Vondrak

- Local search involves switching up to t elements, as long as it provides a (non-trivial) improvement; can iterate in several phases. Some examples follow:
- $1/3$ approximation to unconstrained non-monotone maximization [Feige, Mirrokni, Vondrak, 2007]
- $1/(k + 2 + \frac{1}{k} + \delta_t)$ approximation for non-monotone maximization subject to k matroids [Lee, Mirrokni, Nagarajan, Sviridenko, 2009]
- $1/(k + \delta_t)$ approximation for monotone submodular maximization subject to $k \geq 2$ matroids [Lee, Sviridenko, Vondrak, 2010].

What About Non-monotone

- Alternatively, we may wish to maximize non-monotone submodular functions. This includes of course graph cuts, and this problem is APX-hard, so maximizing non-monotone functions, even unconstrainedly, is hard.
- If f is an arbitrary submodular function (so neither polymatroidal, nor necessarily positive or negative), then verifying if the maximum of f is positive or negative is already NP-hard.
- Therefore, submodular function max in such case is inapproximable unless $P=NP$ (since any such procedure would give us the sign of the max).
- Thus, any approximation algorithm must be for unipolar submodular functions. E.g., non-negative but otherwise arbitrary submodular functions.
- We may get a $(\frac{1}{3} - \frac{\epsilon}{n})$ approximation for maximizing non-monotone non-negative submodular functions, with most $O(\frac{1}{\epsilon} n^3 \log n)$ function calls using approximate local maxima.

Submodularity and local optima

- Given any submodular function f , a set $S \subseteq V$ is a local maximum of f if $f(S - v) \leq f(S)$ for all $v \in S$ and $f(S + v) \leq f(S)$ for all $v \in V \setminus S$ (i.e., local in a Hamming ball of radius 1).
- The following interesting result is true for any submodular function:

Lemma 14.3.2

Given a submodular function f , if S is a local maximum of f , and $I \subseteq S$ or $I \supseteq S$, then $f(I) \leq f(S)$.

- Idea of proof: Given $v_1, v_2 \in S$, suppose $f(S - v_1) \leq f(S)$ and $f(S - v_2) \leq f(S)$. Submodularity requires $f(S - v_1) + f(S - v_2) \geq f(S) + f(S - v_1 - v_2)$ which would be impossible unless $f(S - v_1 - v_2) \leq f(S)$.
- Similarly, given $v_1, v_2 \notin S$, and $f(S + v_1) \leq f(S)$ and $f(S + v_2) \leq f(S)$. Submodularity requires $f(S + v_1) + f(S + v_2) \geq f(S) + f(S + v_1 + v_2)$ which requires $f(S + v_1 + v_2) \leq f(S)$.

Submodularity and local optima

- Given any submodular function f , a set $S \subseteq V$ is a local maximum of f if $f(S - v) \leq f(S)$ for all $v \in S$ and $f(S + v) \leq f(S)$ for all $v \in V \setminus S$ (i.e., local in a Hamming ball of radius 1).
- The following interesting result is true for any submodular function:

Lemma 14.3.2

Given a submodular function f , if S is a local maximum of f , and $I \subseteq S$ or $I \supseteq S$, then $f(I) \leq f(S)$.

- In other words, once we have identified a local maximum, the two intervals in the Boolean lattice $[\emptyset, S]$ and $[S, V]$ can be ruled out as a possible improvement over S .
- Finding a local maximum is already hard (PLS-complete), but it is possible to find an approximate local maximum relatively efficiently.
- This is the approach that yields the $(\frac{1}{3} - \frac{\epsilon}{n})$ approximation algorithm.

Linear time algorithm unconstrained non-monotone max

- Tight randomized tight $1/2$ approximation algorithm for unconstrained non-monotone non-negative submodular maximization.
- Buchbinder, Feldman, Naor, Schwartz 2012. Recall $[a]_+ = \max(a, 0)$.

Algorithm 2: Randomized Linear-time non-monotone submodular max

```

1 Set  $L \leftarrow \emptyset$ ;  $U \leftarrow V$  /* Lower  $L$ , upper  $U$ . Invariant:  $L \subseteq U$  */;
2 Order elements of  $V = (v_1, v_2, \dots, v_n)$  arbitrarily;
3 for  $i \leftarrow 0 \dots |V|$  do
4    $a \leftarrow [f(v_i|L)]_+$ ;  $b \leftarrow [-f(U|U \setminus \{v_i\})]_+$ ;
5   if  $a = b = 0$  then  $p \leftarrow 1/2$ ;
6   ;
7   else  $p \leftarrow a/(a + b)$ ;
8   ;
9   if Flip of coin with  $\Pr(\text{heads}) = p$  draws heads then
10     $L \leftarrow L \cup \{v_i\}$ ;
11   Otherwise /* if the coin drew tails, an event with prob.  $1 - p$  */
12     $U \leftarrow U \setminus \{v_i\}$ ;
13 return  $L$  (which is the same as  $U$  at this point)

```

Linear time algorithm unconstrained non-monotone max

- Each “sweep” of the algorithm is $O(n)$.
- Running the algorithm $1 \times$ (with an arbitrary variable order) results in a $1/3$ approximation.
- The $1/2$ guarantee is in expected value (the expected solution has the $1/2$ guarantee).
- In practice, run it multiple times, each with a different random permutation of the elements, and then take the cumulative best.
- It may be possible to choose the random order smartly to get better results in practice.

More general still: multiple constraints different types

- In the past several years, there has been a plethora of papers on maximizing both monotone and non-monotone submodular functions under various combinations of one or more knapsack and/or matroid constraints.
- The approximation quality is usually some function of the number of matroids, and is often not a function of the number of knapsacks.
- Often the computational costs of the algorithms are prohibitive (e.g., exponential in k) with large constants, so these algorithms might not scale.
- On the other hand, these algorithms offer deep and interesting intuition into submodular functions, beyond what we have covered here.

Some results on submodular maximization

- As we've seen, we can get $1 - 1/e$ for non-negative monotone submodular (polymatroid) functions with greedy algorithm under cardinality constraints, and this is tight.
- For general matroid, greedy reduces to $1/2$ approximation (as we've seen).
- We can recover $1 - 1/e$ approximation using the continuous greedy algorithm on the multilinear extension and then using pipage rounding to re-integerize the solution (see J. Vondrak's publications).
- More general constraints are possible too, as we see on the next table (for references, see Jan Vondrak's publications <http://theory.stanford.edu/~jvondrak/>).

Submodular Max Summary - From J. Vondrak

Monotone Maximization

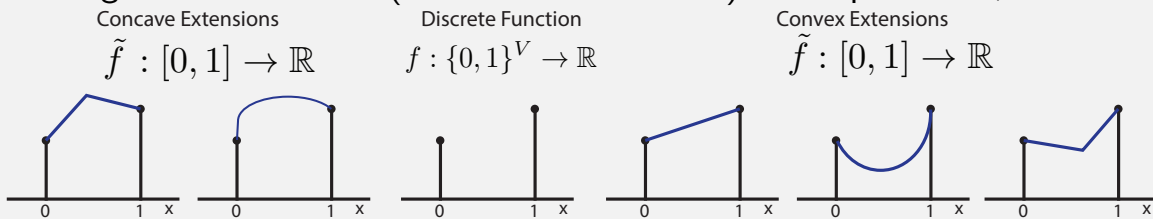
Constraint	Approximation	Hardness	Technique
$ S \leq k$	$1 - 1/e$	$1 - 1/e$	greedy
matroid	$1 - 1/e$	$1 - 1/e$	multilinear ext.
$O(1)$ knapsacks	$1 - 1/e$	$1 - 1/e$	multilinear ext.
k matroids	$k + \epsilon$	$k / \log k$	local search
k matroids and $O(1)$ knapsacks	$O(k)$	$k / \log k$	multilinear ext.

Nonmonotone Maximization

Constraint	Approximation	Hardness	Technique
Unconstrained	$1/2$	$1/2$	combinatorial
matroid	$1/e$	0.48	multilinear ext.
$O(1)$ knapsacks	$1/e$	0.49	multilinear ext.
k matroids	$k + O(1)$	$k / \log k$	local search
k matroids and $O(1)$ knapsacks	$O(k)$	$k / \log k$	multilinear ext.

Continuous Extensions of Discrete Set Functions

- Any function $f : 2^V \rightarrow \mathbb{R}$ (equivalently $f : \{0, 1\}^V \rightarrow \mathbb{R}$) can be extended to a continuous function in the sense $\tilde{f} : [0, 1]^V \rightarrow \mathbb{R}$.
- This may be tight (i.e., $\tilde{f}(\mathbf{1}_A) = f(A)$ for all A). I.e., the extension \tilde{f} coincides with f at the hypercube vertices.
- In fact, any such discrete function defined on the vertices of the n -D hypercube $\{0, 1\}^n$ has a variety of both convex and concave extensions tight at the vertices (Crama & Hammer'11). Example $n = 1$,



- Since there are an exponential number of vertices $\{0, 1\}^n$, important questions regarding such extensions is:
 - When are they computationally feasible to obtain or estimate?
 - When do they have nice mathematical properties?
 - When are they useful for something practical?

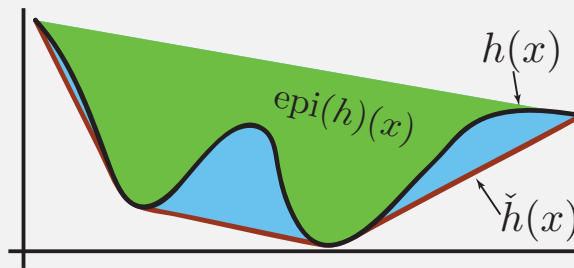
Def: Convex Envelope of a function

- Given any function $h : \mathbb{R}^n \rightarrow \mathbb{R}$, define new function $\check{h} : \mathbb{R}^n \rightarrow \mathbb{R}$ via:

$$\check{h}(x) = \sup \{g(x) : g \text{ is convex \& } g(y) \leq h(y), \forall y \in \mathbb{R}^n\} \quad (14.7)$$

- i.e., (1) $\check{h}(x)$ is convex, (2) $\check{h}(x) \leq h(x), \forall x$, and (3) if $g(x)$ is any convex function having the property that $g(x) \leq h(x), \forall x$, then $g(x) \leq \check{h}(x)$.
- Alternatively,

$$\check{h}(x) = \inf \{t : (x, t) \in \text{convexhull}(\text{epigraph}(h))\} \quad (14.8)$$



Convex Closure of Discrete Set Functions

- Given set function $f : 2^V \rightarrow \mathbb{R}$, an arbitrary (i.e., not necessarily submodular nor supermodular) set function, define a function $\check{f} : [0, 1]^V \rightarrow \mathbb{R}$, as

$$\check{f}(x) = \min_{p \in \Delta^n(x)} \sum_{S \subseteq V} p_S f(S) \quad (14.9)$$

where $\Delta^n(x) =$

$$\left\{ p \in \mathbb{R}^{2^n} : \sum_{S \subseteq V} p_S = 1, p_S \geq 0 \forall S \subseteq V, \& \sum_{S \subseteq V} p_S \mathbf{1}_S = x \right\}$$

- Hence, $\Delta^n(x)$ is the set of all probability distributions over the 2^n vertices of the hypercube, and where the expected value of the characteristic vectors of those points is equal to x , i.e., for any $p \in \Delta^n(x)$, $E_{S \sim p}(\mathbf{1}_S) = \sum_{S \subseteq V} p_S \mathbf{1}_S = x$.
- Hence, $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$
- Note, this is not (necessarily) the Lovász extension, rather this is a convex extension.

Convex Closure of Discrete Set Functions

- Given, $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$, there are several things we'd like to show:
 - That \check{f} is tight (i.e., $\forall S \subseteq V$, we have $\check{f}(\mathbf{1}_S) = f(S)$).
 - That \check{f} is convex (and consequently, that any arbitrary set function has a tight convex extension).
 - That the convex closure \check{f} is the convex envelope of the function defined only on the hypercube vertices, and that takes value $f(S)$ at $\mathbf{1}_S$.
 - The definition of the Lovász extension of a set function, and that \check{f} is the Lovász extension iff f is submodular.

Tightness of Convex Closure

Lemma 14.4.1

$\forall A \subseteq V$, we have $\check{f}(\mathbf{1}_A) = f(A)$.

Proof.

- Define p^x to be an achieving argmin in $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$.
- Take an arbitrary A , so that $\mathbf{1}_A = \sum_{S \subseteq V} p_S^{\mathbf{1}_A} \mathbf{1}_S = \mathbf{1}_A$.
- Suppose $\exists S'$ with $S' \setminus A \neq \emptyset$ having $p_{S'}^{\mathbf{1}_A} > 0$. This would mean, for any $v \in S' \setminus A$, that $(\sum_S p_S^{\mathbf{1}_A} \mathbf{1}_S)(v) > 0$, a contradiction.
- Suppose $\exists S'$ s.t. $A \setminus S' \neq \emptyset$ with $p_{S'}^{\mathbf{1}_A} > 0$.
- Then, for any $v \in A \setminus S'$, consider below leading to a contradiction

$$\underbrace{p_{S'} \mathbf{1}_{S'}}_{>0} + \underbrace{\sum_{\substack{S \subseteq A \\ S \neq S'}} p_S \mathbf{1}_S}_{\text{can't sum to 1}} \Rightarrow \left(\sum_{\substack{S \subseteq A \\ S \neq S'}} p_S \mathbf{1}_S \right)(v) < 1 \quad (14.10)$$

i.e., $v \in A$ so it must get value 1, but since $v \notin S'$, v is deficient. \square

Convexity of the Convex Closure

Lemma 14.4.2

$\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$ is convex in $[0, 1]^V$.

Proof.

- Let $x, y \in [0, 1]^V$, $0 \leq \lambda \leq 1$, and $z = \lambda x + (1 - \lambda)y$, then

$$\lambda \check{f}(x) + (1 - \lambda) \check{f}(y) = \lambda \sum_S p_S^x f(S) + (1 - \lambda) \sum_S p_S^y f(S) \quad (14.11)$$

$$= \sum_S (\lambda p_S^x + (1 - \lambda) p_S^y) f(S) \quad (14.12)$$

$$= \sum_S p_S^{z'} f(S) \geq \min_{p \in \Delta^n(z)} E_{S \sim p}[f(S)] \quad (14.13)$$

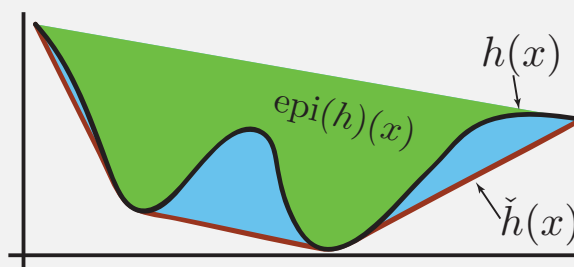
$$= \check{f}(z) = \check{f}(\lambda x + (1 - \lambda)y) \quad (14.14)$$
- Note that $p_S^{z'} = \lambda p_S^x + (1 - \lambda) p_S^y$ and is feasible in the min since $\sum_S p_S^{z'} = 1$, $p_S^{z'} \geq 0$ and $\sum_S p_S^{z'} \mathbf{1}_S = z$.

Def: Convex Envelope of a function

- Given any function $h : \mathbb{R}^n \rightarrow \mathbb{R}$, define new function $\check{h} : \mathbb{R}^n \rightarrow \mathbb{R}$ via:

$$\check{h}(x) = \sup \{g(x) : g \text{ is convex \& } g(y) \leq h(y), \forall y \in \mathbb{R}^n\} \quad (14.7)$$
- i.e., (1) $\check{h}(x)$ is convex, (2) $\check{h}(x) \leq h(x), \forall x$, and (3) if $g(x)$ is any convex function having the property that $g(x) \leq h(x), \forall x$, then $g(x) \leq \check{h}(x)$.
- Alternatively,

$$\check{h}(x) = \inf \{t : (x, t) \in \text{convexhull}(\text{epigraph}(h))\} \quad (14.8)$$



Convex Closure is the Convex Envelope

Lemma 14.4.3

$\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$ is the convex envelope.

Proof.

- Suppose \exists a convex \bar{f} with $\bar{f}(\mathbf{1}_A) = f(A) = \check{f}(\mathbf{1}_A), \forall A \subseteq V$ and $\exists x \in [0, 1]^V$ s.t. $\bar{f}(x) > \check{f}(x)$.
- Define p^x to be an achieving argmin in $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$. Hence, we have $x = \sum_S p_S^x \mathbf{1}_S$. Thus

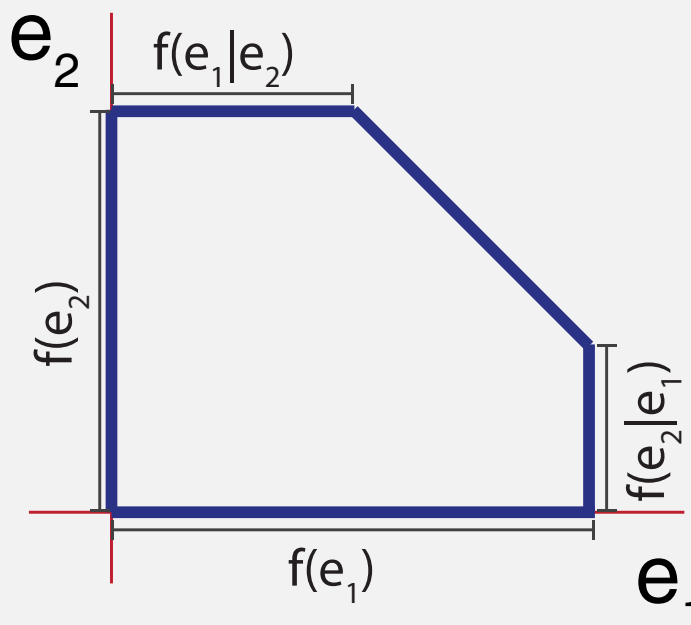
$$\check{f}(x) = \sum_S p_S^x f(S) = \sum_S p_S^x \bar{f}(\mathbf{1}_S) \quad (14.15)$$

$$< \bar{f}(x) = \bar{f}\left(\sum_S p_S^x \mathbf{1}_S\right) \quad (14.16)$$

but this contradicts the convexity of \bar{f} .

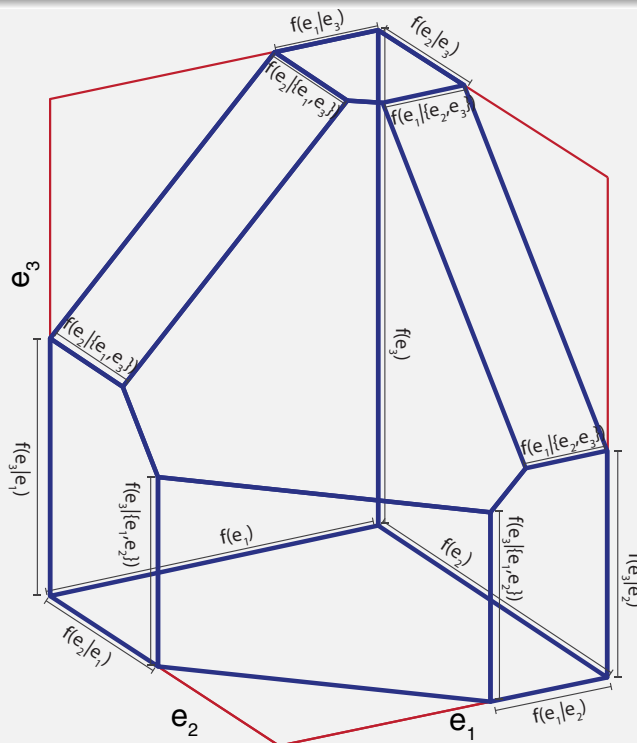
Polymatroid with labeled edge lengths

- Recall $f(e|A) = f(A+e) - f(A)$
- Notice how submodularity, $f(e|B) \leq f(e|A)$ for $A \subseteq B$, defines the shape of the polytope.
- In fact, we have strictness here $f(e|B) < f(e|A)$ for $A \subset B$.
- Also, consider how the greedy algorithm proceeds along the edges of the polytope.



Polymatroid with labeled edge lengths

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- Notice how submodularity, $f(e|B) \leq f(e|A)$ for $A \subseteq B$, defines the shape of the polytope.
- In fact, we have strictness here $f(e|B) < f(e|A)$ for $A \subset B$.
- Also, consider how the greedy algorithm proceeds along the edges of the polytope.



Optimization over P_f

- Consider the following optimization. Given $w \in \mathbb{R}^E$,

$$\text{maximize} \quad w^\top x \quad (14.17a)$$

$$\text{subject to} \quad x \in P_f \quad (14.17b)$$

- Since P_f is down closed, if $\exists e \in E$ with $w(e) < 0$ then the solution above is unboundedly large. Hence, assume $w \in \mathbb{R}_+^E$.
- Due to Theorem ??, any $x \in P_f$ with $x \notin B_f$ is dominated by $x \leq y \in B_f$ which can only increase $w^\top x \leq w^\top y$ when $w \in \mathbb{R}_+^E$.
- Hence, the problem is equivalent to: given $w \in \mathbb{R}_+^E$,

$$\text{maximize} \quad w^\top x \quad (14.18a)$$

$$\text{subject to} \quad x \in B_f \quad (14.18b)$$

- Moreover, we can have $w \in \mathbb{R}^E$ if we insist on $x \in B_f$.

A continuous extension of f

- Consider again optimization problem. Given $w \in \mathbb{R}^E$,

$$\text{maximize} \quad w^\top x \quad (14.19a)$$

$$\text{subject to} \quad x \in B_f \quad (14.19b)$$

- We may consider this optimization problem a function $\check{f} : \mathbb{R}^E \rightarrow \mathbb{R}$ of $w \in \mathbb{R}^E$, defined as:

$$\check{f}(w) = \max\{wx : x \in B_f\} \quad (14.20)$$

- Hence, for any w , from the solution to the above theorem (as we have seen), we can compute the value of this function using Edmond's greedy algorithm.

Edmond's Theorem: The Greedy Algorithm

- Edmonds proved that the solution to $\check{f}(w) = \max\{wx : x \in B_f\}$ is solved by the greedy algorithm iff f is submodular.
- In particular, sort choose element order (e_1, e_2, \dots, e_m) based on decreasing w , so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$.
- Define the chain with i^{th} element $E_i = \{e_1, e_2, \dots, e_i\}$.
- Define a vector $x^* \in \mathbb{R}^V$ where element e_i has value $x(e_i) = f(e_i | E_{i-1})$ for all $i \in V$.
- Then $\langle w, x^* \rangle = \max\{wx : x \in B_f\}$

Theorem 14.5.1 (Edmonds)

If $f : 2^E \rightarrow \mathbb{R}_+$ is given, and B is a polytope in \mathbb{R}_+^E of the form $B = \{x \in \mathbb{R}_+^E : x(A) \leq f(A), \forall A \subseteq E, x(E) = f(E)\}$, then the greedy solution to the problem $\max\{w^\top x : x \in P\}$ is $\forall w$ optimum **iff** f is monotone non-decreasing submodular (i.e., iff P is a polymatroid).

A continuous extension of submodular f

- That is, given a submodular function f , a $w \in \mathbb{R}^E$, choose element order (e_1, e_2, \dots, e_m) based on decreasing w , so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$.
- Define the chain with i^{th} element $E_i = \{e_1, e_2, \dots, e_i\}$, we have

$$\check{f}(w) = \max(wx : x \in B_f) \quad (14.21)$$

$$= \sum_{i=1}^m w(e_i) f(e_i | E_{i-1}) = \sum_{i=1}^m w(e_i) x(e_i) \quad (14.22)$$

$$= \sum_{i=1}^m w(e_i) (f(E_i) - f(E_{i-1})) \quad (14.23)$$

$$= w(e_m) f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1})) f(E_i) \quad (14.24)$$

- We say that $\emptyset \triangleq E_0 \subset E_1 \subset E_2 \subset \dots \subset E_m = E$ forms a **chain** based on w .

A continuous extension of submodular f

- Definition of the continuous extension, once again, for reference:

$$\check{f}(w) = \max(wx : x \in B_f) \quad (14.25)$$

- Therefore, if f is a submodular function, we can write

$$\check{f}(w) = w(e_m) f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1})) f(E_i) \quad (14.26)$$

$$= \sum_{i=1}^m \lambda_i f(E_i) \quad (14.27)$$

where $\lambda_m = w(e_m)$ and otherwise $\lambda_i = w(e_i) - w(e_{i+1})$, where the elements are sorted descending according to w as before.

- Convex analysis $\Rightarrow \check{f}(w) = \max(wx : x \in P)$ is always convex in w for any set $P \subseteq \mathbb{R}^E$, since a maximum of a set of linear functions (true even when f is not submodular or P is not itself a convex set).

An extension of f

- Recall, for any such $w \in \mathbb{R}^E$, we have

$$\begin{aligned} \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} &= \underbrace{(w_1 - w_2)}_{\lambda_1} \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{(w_2 - w_3)}_{\lambda_2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \\ &\dots + \underbrace{(w_{n-1} - w_n)}_{\lambda_{m-1}} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \end{pmatrix} + \underbrace{(w_m)}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{pmatrix} \end{aligned} \tag{14.28}$$

- If we take w in decreasing order, then each coefficient of the vectors is non-negative (except possibly the last one, $\lambda_m = w_m$).
- Often, we take $w \in \mathbb{R}_+^V$ or even $w \in [0, 1]^V$, where $\lambda_m \geq 0$.

An extension of f

- Define sets E_i based on this decreasing order of w as follows, for $i = 0, \dots, n$

$$E_i \stackrel{\text{def}}{=} \{e_1, e_2, \dots, e_i\} \tag{14.29}$$

- Note that

$$\mathbf{1}_{E_0} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \mathbf{1}_{E_1} = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \dots, \mathbf{1}_{E_\ell} = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \text{ etc.}$$

$\left. \begin{matrix} \vdots \\ \vdots \\ \vdots \end{matrix} \right\} \ell \times$
 $\left. \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \right\} (n - \ell) \times$

- Hence, from the previous and current slide, we have $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$

From \check{f} back to f , even when f is not submodular

- From the continuous \check{f} , we can recover $f(A)$ for any $A \subseteq V$.
- Take $w = \mathbf{1}_A$ for some $A \subseteq E$, so w is vertex of the hypercube.
- Order the elements of E in decreasing order of w so that $w(e_1) \geq w(e_2) \geq w(e_3) \geq \dots \geq w(e_m)$.
- This means

$$w = (w(e_1), w(e_2), \dots, w(e_m)) = (\underbrace{1, 1, 1, \dots, 1}_{|A| \text{ times}}, \underbrace{0, 0, \dots, 0}_{m-|A| \text{ times}}) \quad (14.30)$$

so that $\mathbf{1}_A(i) = 1$ if $i \leq |A|$, and $\mathbf{1}_A(i) = 0$ otherwise.

- For any $f : 2^E \rightarrow \mathbb{R}$, $w = \mathbf{1}_A$, since $E_{|A|} = \{e_1, e_2, \dots, e_{|A|}\} = A$:

$$\begin{aligned} \check{f}(w) &= \sum_{i=1}^m \lambda_i f(E_i) = w(e_m) f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1})) f(E_i) \\ &= \mathbf{1}_A(m) f(E_m) + \sum_{i=1}^{m-1} (\mathbf{1}_A(i) - \mathbf{1}_A(i+1)) f(E_i) \end{aligned} \quad (14.31)$$

$$= (\mathbf{1}_A(|A|) - \mathbf{1}_A(|A| + 1)) f(E_{|A|}) = f(E_{|A|}) = f(A) \quad (14.32)$$

From \check{f} back to f

- We can view $\check{f} : [0, 1]^E \rightarrow \mathbb{R}$ defined on the hypercube, with f defined as \check{f} evaluated on the hypercube extreme points (vertices).
- To summarize, with $\check{f}(\mathbf{1}_A) = \sum_{i=1}^m \lambda_i f(E_i)$, we have

$$\check{f}(\mathbf{1}_A) = f(A), \quad (14.33)$$

- ... and when f is submodular, we also have have

$$\check{f}(\mathbf{1}_A) = \max \{ \mathbf{1}_A^\top x : x \in B_f \} \quad (14.34)$$

$$= \max \{ \mathbf{1}_A^\top x : x(B) \leq f(B), \forall B \subseteq E \} \quad (14.35)$$

- Note when considering only $\check{f} : [0, 1]^E \rightarrow \mathbb{R}$, then any $w \in [0, 1]^E$ is in positive orthant, and we have

$$\check{f}(w) = \max \{ w^\top x : x \in P_f \} \quad (14.36)$$

An extension of an arbitrary $f : 2^V \rightarrow \mathbb{R}$

- Thus, for any $f : 2^E \rightarrow \mathbb{R}$, even non-submodular f , we can define an extension, having $\check{f}(\mathbf{1}_A) = f(A)$, $\forall A$, in this way where

$$\check{f}(w) = \sum_{i=1}^m \lambda_i f(E_i) \tag{14.37}$$

with the $E_i = \{e_1, \dots, e_i\}$'s defined based on sorted descending order of w as in $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$, and where

$$\text{for } i \in \{1, \dots, m\}, \quad \lambda_i = \begin{cases} w(e_i) - w(e_{i+1}) & \text{if } i < m \\ w(e_m) & \text{if } i = m \end{cases} \tag{14.38}$$

so that $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$.

- $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$ is an interpolation of certain hypercube vertices.
- $\check{f}(w) = \sum_{i=1}^m \lambda_i f(E_i)$ is the associated interpolation of the values of f at sets corresponding to each hypercube vertex.
- **This extension is called the Lovász extension!**

Weighted gains vs. weighted functions

- Again sorting E descending in w , the extension summarized:

$$\check{f}(w) = \sum_{i=1}^m w(e_i) f(e_i | E_{i-1}) \tag{14.39}$$

$$= \sum_{i=1}^m w(e_i) (f(E_i) - f(E_{i-1})) \tag{14.40}$$

$$= w(e_m) f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1})) f(E_i) \tag{14.41}$$

$$= \sum_{i=1}^m \lambda_i f(E_i) \tag{14.42}$$

- So $\check{f}(w)$ seen either as **sum of weighted gain evaluations** (Eqn. (14.39)), or as **sum of weighted function evaluations** (Eqn. (14.42)).

Summary: comparison of the two extension forms

- So if f is submodular, then we can write $\check{f}(w) = \max\{wx : x \in B_f\}$ (which is clearly convex) in the form:

$$\check{f}(w) = \max\{wx : x \in B_f\} = \sum_{i=1}^m \lambda_i f(E_i) \tag{14.43}$$

where $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$ and $E_i = \{e_1, \dots, e_i\}$ defined based on sorted descending order $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$.

- On the other hand, for any f (even non-submodular), we can produce an extension \check{f} having the form

$$\check{f}(w) = \sum_{i=1}^m \lambda_i f(E_i) \tag{14.44}$$

where $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$ and $E_i = \{e_1, \dots, e_i\}$ defined based on sorted descending order $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$.

- In both Eq. (14.43) and Eq. (14.44), we have $\check{f}(\mathbf{1}_A) = f(A), \forall A$, but Eq. (14.44), might not be convex.
- Submodularity is sufficient for convexity, but is it necessary?

The Lovász extension of $f : 2^E \rightarrow \mathbb{R}$

- Lovász showed that if a function $\check{f}(w)$ defined as in Eqn. (14.37) is convex, then f must be submodular.
- This continuous extension \check{f} of f , in any case (f being submodular or not), is typically called the Lovász extension of f (but also sometimes called the Choquet integral, or the Lovász-Edmonds extension).

Lovász Extension, Submodularity and Convexity

Theorem 14.5.2

A function $f : 2^E \rightarrow \mathbb{R}$ is submodular iff its Lovász extension \check{f} of f is convex.

Proof.

- We've already seen that if f is submodular, its extension can be written via Eqn.(14.37) due to the greedy algorithm, and therefore is also equivalent to $\check{f}(w) = \max \{wx : x \in P_f\}$, and thus is convex.
- Conversely, suppose the Lovász extension $\check{f}(w) = \sum_i \lambda_i f(E_i)$ of some function $f : 2^E \rightarrow \mathbb{R}$ is a convex function.
- We note that, based on the extension definition, in particular the definition of the $\{\lambda_i\}_i$, we have that $\check{f}(\alpha w) = \alpha \check{f}(w)$ for any $\alpha \in \mathbb{R}_+$. I.e., f is a positively homogeneous convex function.

...

Lovász Extension, Submodularity and Convexity

... proof of Thm. 14.5.2 cont.

- Earlier, we saw that $\check{f}(\mathbf{1}_A) = f(A)$ for all $A \subseteq E$.
- Now, given $A, B \subseteq E$, we will show that

$$\check{f}(\mathbf{1}_A + \mathbf{1}_B) = \check{f}(\mathbf{1}_{A \cup B} + \mathbf{1}_{A \cap B}) \quad (14.45)$$

$$= f(A \cup B) + f(A \cap B). \quad (14.46)$$

- Let $C = A \cap B$, order E based on decreasing $w = \mathbf{1}_A + \mathbf{1}_B$ so that

$$w = (w(e_1), w(e_2), \dots, w(e_m)) \quad (14.47)$$

$$= (\underbrace{2, 2, \dots, 2}_{i \in C}, \underbrace{1, 1, \dots, 1}_{i \in A \Delta B}, \underbrace{0, 0, \dots, 0}_{i \in E \setminus (A \cup B)}) \quad (14.48)$$

- Then, considering $\check{f}(w) = \sum_i \lambda_i f(E_i)$, we have $\lambda_{|C|} = 1$, $\lambda_{|A \cup B|} = 1$, and $\lambda_i = 0$ for $i \notin \{|C|, |A \cup B|\}$.
- But then $E_{|C|} = A \cap B$ and $E_{|A \cup B|} = A \cup B$. Therefore, $\check{f}(w) = \check{f}(\mathbf{1}_A + \mathbf{1}_B) = f(A \cap B) + f(A \cup B)$.

...

Lovász Extension, Submodularity and Convexity

... proof of Thm. 14.5.2 cont.

- Also, since \check{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\check{f}(\mathbf{1}_A + \mathbf{1}_B)] \quad (14.49)$$

$$= \check{f}(0.5\mathbf{1}_A + 0.5\mathbf{1}_B) \quad (14.50)$$

$$\leq 0.5\check{f}(\mathbf{1}_A) + 0.5\check{f}(\mathbf{1}_B) \quad (14.51)$$

$$= 0.5(f(A) + f(B)) \quad (14.52)$$

- Thus, we have shown that for any $A, B \subseteq E$,

$$f(A \cup B) + f(A \cap B) \leq f(A) + f(B) \quad (14.53)$$

so f must be submodular. □

Lovász ext. vs. the concave closure of submodular function

- The above theorem showed that the Lovász extension is convex iff f is submodular.
- Our next theorem shows that the Lovász extension coincides precisely with the convex closure iff f is submodular.
- I.e., not only is the Lovász extension convex for f submodular, it is the convex closure when f is convex.
- Hence, convex closure is easy to evaluate when f is submodular and is this particular form iff f is submodular.

Lovász ext. vs. the concave closure of submodular function

Theorem 14.5.3

Let $\check{f}(w) = \max\{wx : x \in B_f\} = \sum_{i=1}^m \lambda_i f(E_i)$ be the Lovász extension and $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$ be the concave closure. Then \check{f} and \check{f} coincide iff f is submodular.

Proof.

- Assume f is submodular.
- Given x , let p^x be an achieving argmin in $\check{f}(x)$ that also maximizes $\sum_S p_S^x |S|^2$.
- Suppose $\exists A, B \subseteq V$ that are crossing (i.e., $A \not\subseteq B, B \not\subseteq A$) and positive and w.l.o.g., $p_A^x \geq p_B^x > 0$.
- Then we may update p^x as follows:

$$\bar{p}_A^x \leftarrow p_A^x - p_B^x \quad \bar{p}_B^x \leftarrow p_B^x - p_A^x \quad (14.54)$$

$$\bar{p}_{A \cup B}^x \leftarrow p_{A \cup B}^x + p_B^x \quad \bar{p}_{A \cap B}^x \leftarrow p_{A \cap B}^x + p_A^x \quad (14.55)$$

and by submodularity, this does not increase $\sum_S p_S^x f(S)$.

...

Lovász ext. vs. the concave closure of submodular function

... proof cont.

- This does increase $\sum_S p_S^x |S|^2$ however since

$$|A \cup B|^2 + |A \cap B|^2 = (|A| + |B \setminus A|)^2 + (|B| - |B \setminus A|)^2 \quad (14.56)$$

$$= |A|^2 + |B|^2 + 2|B \setminus A|(|A| - |B| + |B \setminus A|) \quad (14.57)$$

$$\geq |A|^2 + |B|^2 \quad (14.58)$$

- Contradiction! Hence, there can be no crossing sets A, B and we must have, for any A, B with $p_A^x > 0$ and $p_B^x > 0$ either $A \subseteq B$ or $B \subseteq A$.
- Hence, the sets $\{A \subseteq V : p_A^x > 0\}$ form a chain and can be as large only as size $n = |V|$.
- This is the same chain that defines the Lovász extension $\check{f}(x)$, namely $\emptyset = E_0 \subseteq E_1 \subseteq E_2 \subseteq \dots$ where $E_i = \{e_1, e_2, \dots, e_i\}$ and e_i is ordered so that $x(e_1) \geq x(e_2) \geq \dots \geq x(e_n)$.

Lovász ext. vs. the concave closure of submodular function

... proof cont.

- Next, assume f is not submodular. We must show that the Lovász extension $\check{f}(x)$ and the concave closure $\check{\check{f}}(x)$ need not coincide.
- Since f is not submodular, $\exists S$ and $i, j \notin S$ such that $f(S) + f(S + i + j) > f(S + i) + f(S + j)$, a strict violation of submodularity.
- Consider $x = \mathbf{1}_S + \frac{1}{2}\mathbf{1}_{\{i,j\}}$.
- Then $\check{f}(x) = \frac{1}{2}f(S) + \frac{1}{2}f(S + i + j)$ and p^x is feasible for \check{f} with $p_S^x = 1/2$ and $p_{S+i+j}^x = 1/2$.
- An alternate feasible distribution for x in the convex closure is $\bar{p}_{S+i}^x = \bar{p}_{S+j}^x = 1/2$.
- This gives

$$\check{f}(x) \leq \frac{1}{2}[f(S + i) + f(S + j)] < \check{\check{f}}(x) \quad (14.59)$$

meaning $\check{f}(x) \neq \check{\check{f}}(x)$. □