Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 9 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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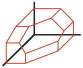
$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$

$= f(A_r) + 2f(C) + f(B_r)$ $\quad = f(A_r) + f(C) + f(B_r)$ $\quad = f(A \cap B)$



Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.
- Read chapter 2 from Fujishige's book.

Announcements, Assignments, and Reminders

- If you have any questions about anything, please ask then via our discussion board (https://canvas.uw.edu/courses/1216339/discussion_topics).

Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions,
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9): More Examples/Properties/ Other Submodular Defs., Independence,
- L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar Matroids
- L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
- L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
- L9(4/23): Polyhedra, Matroid Polytopes, Matroids $\rightarrow$ Polymatroids
- L10(4/25):
- L11(4/30):
- L12(5/2):
- L13(5/7):
- L14(5/9):
- L15(5/14):
- L16(5/16):
- L17(5/21):
- L18(5/23):
- L–(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

Last day of instruction, June 1st. Finals Week: June 2-8, 2018.

The greedy algorithm

- In combinatorial optimization, the greedy algorithm is often useful as a heuristic that can work quite well in practice.
- The goal is to choose a good subset of items, and the fundamental tenet of the greedy algorithm is to choose next whatever currently looks best, without the possibility of later recall or backtracking.
- Sometimes, this gives the optimal solution (we saw three greedy algorithms that can find the maximum weight spanning tree).
- Greedy is good since it can be made to run very fast $O(n \log n)$.
- Often, however, greedy is heuristic (it might work well in practice, but worst-case performance can be unboundedly poor).
- We will next see that the greedy algorithm working optimally is a defining property of a matroid, and is also a defining property of a polymatroid function.

Matroid and the greedy algorithm

- Let $(E, \mathcal{I})$ be an independence system, and we are given a non-negative modular weight function $w : E \to \mathbb{R}_+$.

Algorithm 1: The Matroid Greedy Algorithm

Set $X \leftarrow \emptyset$;
while $\exists v \in E \setminus X$ *s.t.* $X \cup \{v\} \in \mathcal{I}$ **do**
  $v \in \operatorname{argmax} \{w(v) : v \in E \setminus X,\ X \cup \{v\} \in \mathcal{I}\}$;
  $X \leftarrow X \cup \{v\}$;

- Same as sorting items by decreasing weight w, and then choosing items in that order that retain independence.

Theorem 9.2.8

Let $(E, \mathcal{I})$ be an independence system. Then the pair $(E, \mathcal{I})$ is a matroid if and only if for each weight function $w \in \mathcal{R}_+^E$, Algorithm ?? above leads to a set $I \in \mathcal{I}$ of maximum weight $w(I)$.

Summary of Important (for us) Matroid Definitions

Given an independence system, matroids are defined equivalently by any of the following:

- All maximally independent sets have the same size.
- A monotone non-decreasing submodular integral rank function with unit increments.
- The greedy algorithm achieves the maximum weight independent set for all weight functions.

Convex Polyhedra

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Definition 9.3.1

A subset $P \subseteq \mathbb{R}^E = \mathbb{R}^m$ is a polyhedron if there exists an $\ell \times m$ matrix A and vector $b \in \mathbb{R}^\ell$ (for some $\ell \geq 0$) such that

$$P = \{x \in \mathbb{R}^E : Ax \leq b\} \tag{9.1}$$

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- Thus, P is intersection of finitely many (ℓ) affine halfspaces, which are of the form $a_i x \leq b_i$ where a_i is a row vector and b_i a real scalar.

Convex Polytope

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Definition 9.3.2

A subset $P \subseteq \mathbb{R}^E = \mathbb{R}^m$ is a polytope if it is the convex hull of finitely many vectors in $\mathbb{R}^E$. That is, if $\exists$, $x_1, x_2, \ldots, x_k \in \mathbb{R}^E$ such that for all $x \in P$, there exits $\{\lambda_i\}$ with $\sum_i \lambda_i = 1$ and $\lambda_i \geq 0 \; \forall i$ with $x = \sum_i \lambda_i x_i$.

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- We define the convex hull operator as follows:

$$\text{conv}(x_1, x_2, \ldots, x_k) \stackrel{\text{def}}{=} \left\{ \sum_{i=1}^{k} \lambda_i x_i : \forall i, \; \lambda_i \geq 0, \text{ and } \sum_i \lambda_i = 1 \right\} \tag{9.2}$$

Convex Polytope - key representation theorem

- A polytope can be defined in a number of ways, two of which include

Theorem 9.3.3

A subset $P \subseteq \mathbb{R}^E$ is a polytope iff it can be described in either of the following (equivalent) ways:

- *P is the convex hull of a finite set of points.*
- *If it is a bounded intersection of halfspaces, that is there exits matrix A and vector b such that*

$$P = \{x : Ax \leq b\} \tag{9.3}$$

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- This result follows directly from results proven by Fourier, Motzkin, Farkas, and Carátheodory.

Linear Programming

Theorem 9.3.4 (weak duality)

Let A be a matrix and b and c vectors, then

$$\max\{c^\intercal x | Ax \le b\} \le \min\{y^\intercal b : y \ge 0, y^\intercal A = c^\intercal\} \tag{9.4}$$

Linear Programming

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Theorem 9.3.5 (strong duality)

Let A be a matrix and b and c vectors, then

$$\max \{c^\intercal x | Ax \leq b\} = \min \{y^\intercal b : y \geq 0, y^\intercal A = c^\intercal\} \tag{9.5}$$

Linear Programming duality forms

There are many ways to construct the dual. For example,

$$\max\{c^\intercal x | x \geq 0, Ax \leq b\} = \min\{y^\intercal b | y \geq 0, y^\intercal A \geq c^\intercal\} \tag{9.6}$$

$$\max\{c^\intercal x | x \geq 0, Ax = b\} = \min\{y^\intercal b | y^\intercal A \geq c^\intercal\} \tag{9.7}$$

$$\min\{c^\intercal x | x \geq 0, Ax \geq b\} = \max\{y^\intercal b | y \geq 0, y^\intercal A \leq c^\intercal\} \tag{9.8}$$

$$\min\{c^\intercal x | Ax \geq b\} = \max\{y^\intercal b | y \geq 0, y^\intercal A = c^\intercal\} \tag{9.9}$$

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> *Intuitively, why is [one set of equations] the dual of [another quite different set of equations]? In our experience, this is not the right question to be asked. As stated in Section 12.1, there is a purely mechanical procedure for obtaining the dual of a linear program. Once the dual is obtained, one can devise intuitive, and possibly physical meaningful, ways of thinking about it. Using this mechanical procedure, one can obtain the dual of a complex linear program in a fairly straightforward manner. Indeed, the LP-duality-based approach derives its wide applicability from this fact.*

Also see the text "Convex Optimization" by Boyd and Vandenberghe, chapter 5, for a great discussion on duality and easy mechanical ways to construct it.

Vector, modular, incidence

- Recall, any vector $x \in \mathbb{R}^E$ can be seen as a normalized modular function, as for any $A \subseteq E$, we have

$$x(A) = \sum_{a \in A} x_a \tag{9.10}$$

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- Given an $A \subseteq E$, define the incidence vector $\mathbf{1}_A \in \{0,1\}^E$ on the unit hypercube as follows:

$$\mathbf{1}_A \stackrel{\text{def}}{=} \left\{ x \in \{0,1\}^E : x_i = 1 \text{ iff } i \in A \right\} \tag{9.11}$$

equivalently,

$$\mathbf{1}_A(j) \stackrel{\text{def}}{=} \begin{cases} 1 & \text{if } j \in A \\ 0 & \text{if } j \notin A \end{cases} \tag{9.12}$$

Review from Lecture 6

The next slide is review from lecture 6.

Matroid

Slight modification (non unit increment) that is equivalent.

Definition 9.4.3 (Matroid-II)

A set system $(E, \mathcal{I})$ is a Matroid if

(I1') $\emptyset \in \mathcal{I}$

(I2') $\forall I \in \mathcal{I}, J \subset I \Rightarrow J \in \mathcal{I}$ (down-closed or subclusive)

(I3') $\forall I, J \in \mathcal{I}$, with $|I| > |J|$, then there exists $x \in I \setminus J$ such that $J \cup \{x\} \in \mathcal{I}$

Note (I1)=(I1'), (I2)=(I2'), and we get (I3)≡(I3') using induction.

Independence Polyhedra

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- Taking the convex hull, we get the independent set polytope, that is

$$P_{\text{ind. set}} = \text{conv}\left\{ \bigcup_{I \in \mathcal{I}} \{\mathbf{1}_I\} \right\} \subseteq [0,1]^E \tag{9.13}$$

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- Since $\{\mathbf{1}_I : I \in \mathcal{I}\} \subseteq P_{\text{ind. set}} \subseteq P_r^+$, we have $\max\{w(I) : I \in \mathcal{I}\} \leq \max\{w^\intercal x : x \in P_{\text{ind. set}}\} \leq \max\{w^\intercal x : x \in P_r^+\}$

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- Now take the rank function r of M, and define the following polyhedron:

$$P_r^+ \triangleq \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r(A), \forall A \subseteq E\} \tag{9.14}$$

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- Now, take any $x \in P_{\text{ind. set}}$, then we have that $x \in P_r^+$ (or $P_{\text{ind. set}} \subseteq P_r^+$). We show this next.

$P_{\text{ind. set}} \subseteq P_r^+$

- If $x \in P_{\text{ind. set}}$, then

$$x = \sum_i \lambda_i \mathbf{1}_{I_i} \tag{9.15}$$

for some appropriate vector $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_n)$.

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$$\leq \sum_i \lambda_i \max_{j : I_j \subseteq A} \mathbf{1}_{I_j}(E) \tag{9.17}$$

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$$= r(A) \tag{9.19}$$

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- Clearly, for such x, $x \geq 0$.
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- Thus, $x \in P_r^+$ and hence $P_{\text{ind. set}} \subseteq P_r^+$.

Matroid Polyhedron in 2D

$$P_r^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r(A), \forall A \subseteq E\} \tag{9.20}$$

- Consider this in two dimensions. We have equations of the form:

$$x_1 \geq 0 \text{ and } x_2 \geq 0 \tag{9.21}$$

$$x_1 \leq r(\{v_1\}) \in \{0, 1\} \tag{9.22}$$

$$x_2 \leq r(\{v_2\}) \in \{0, 1\} \tag{9.23}$$

$$x_1 + x_2 \leq r(\{v_1, v_2\}) \in \{0, 1, 2\} \tag{9.24}$$

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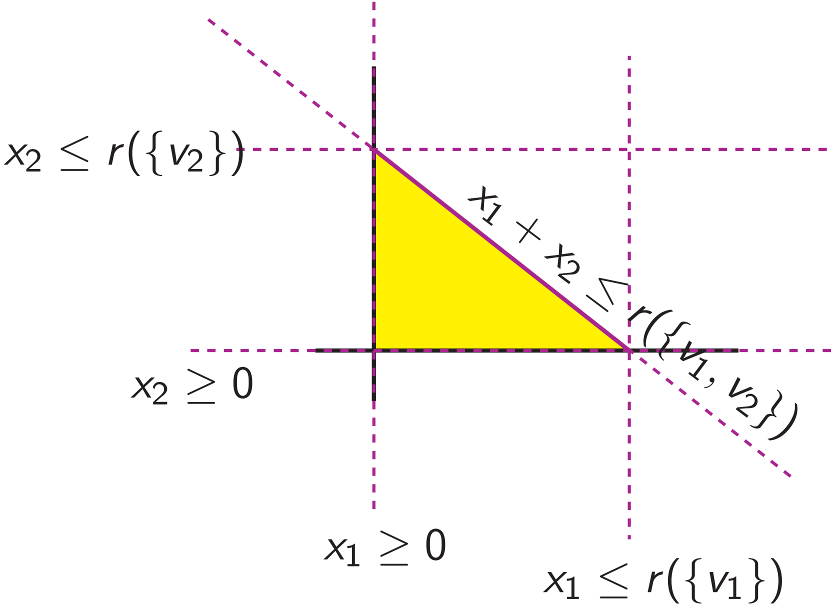
$$x_1 + x_2 \leq r(\{v_1, v_2\}) \in \{0, 1, 2\} \tag{9.24}$$

- Because r is submodular, we have

$$r(\{v_1\}) + r(\{v_2\}) \geq r(\{v_1, v_2\}) + r(\emptyset) \tag{9.25}$$

so since $r(\{v_1, v_2\}) \leq r(\{v_1\}) + r(\{v_2\})$, the last inequality is either touching ($r(v_1, v_2) = r(v_1) + r(v_2)$, inactive) or active.

Matroid Polyhedron in 2D



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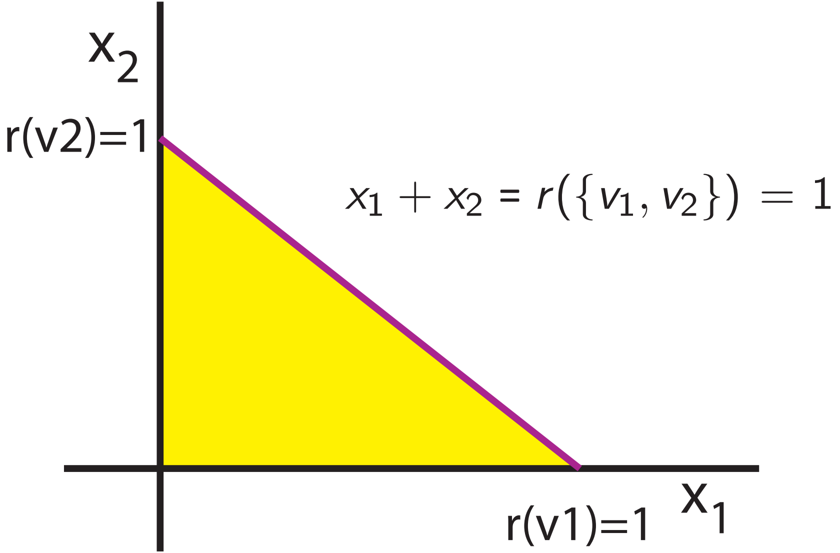

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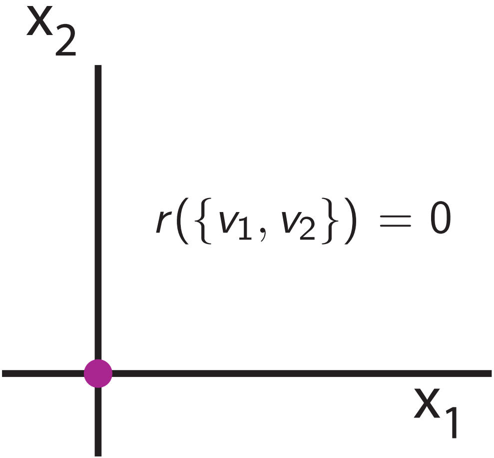

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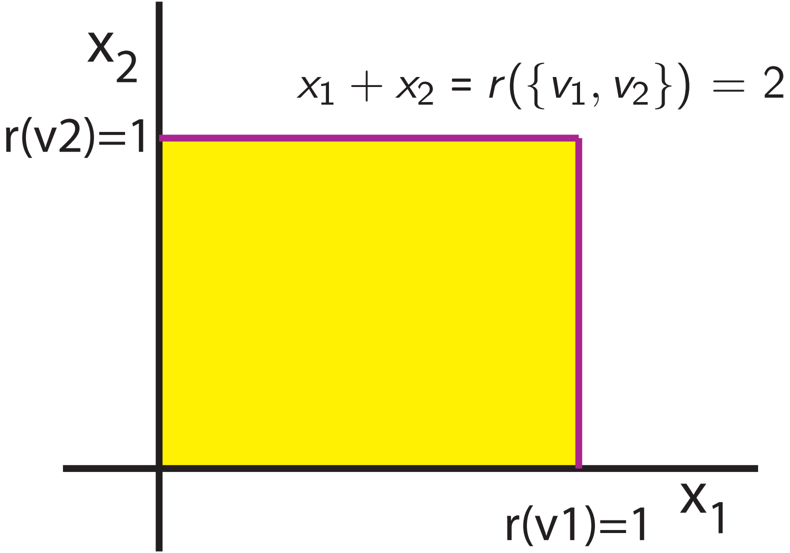
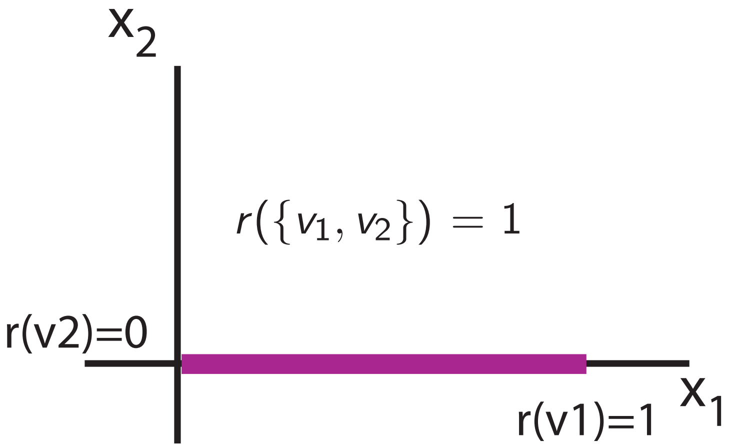


Matroid Polyhedron in 2D

And, if v2 is a loop ...



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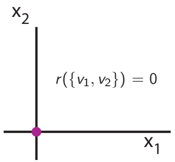

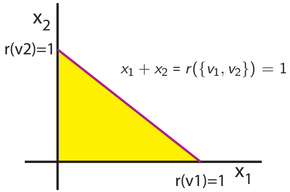

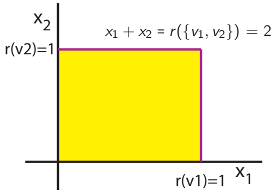

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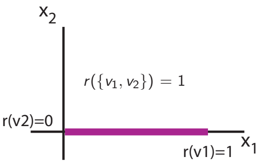

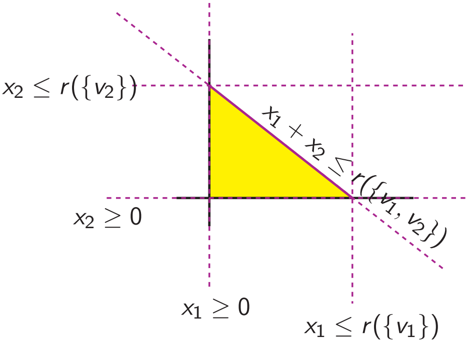

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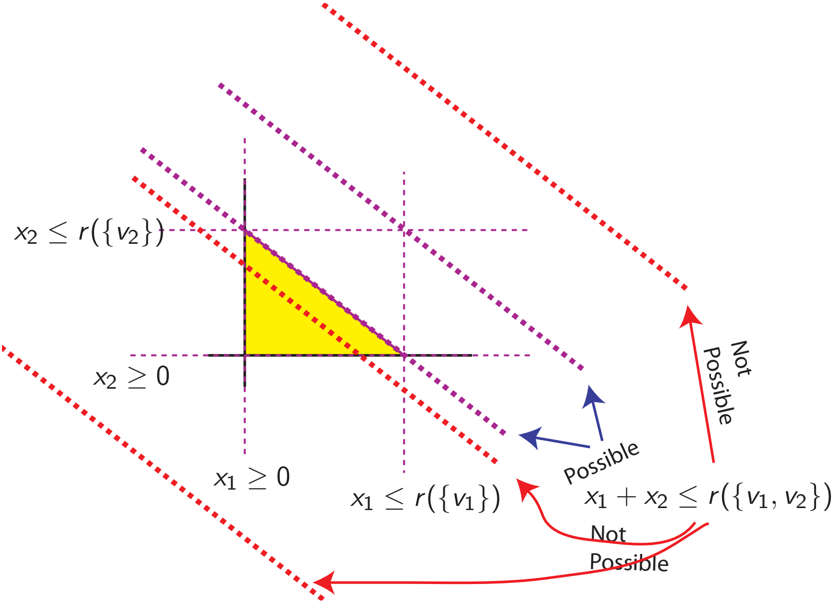

Matroid Polyhedron in 3D

$$P_r^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r(A), \forall A \subseteq E\} \tag{9.26}$$

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$$x_1 + x_3 \leq r(\{v_1, v_3\}) \tag{9.33}$$

$$x_1 + x_2 + x_3 \leq r(\{v_1, v_2, v_3\}) \tag{9.34}$$

Matroid Polyhedron in 3D

- Consider the simple cycle matroid on a graph consisting of a 3-cycle, $G = (V, E)$ with matroid $M = (E, \mathcal{I})$ where $I \in \mathcal{I}$ is a forest.

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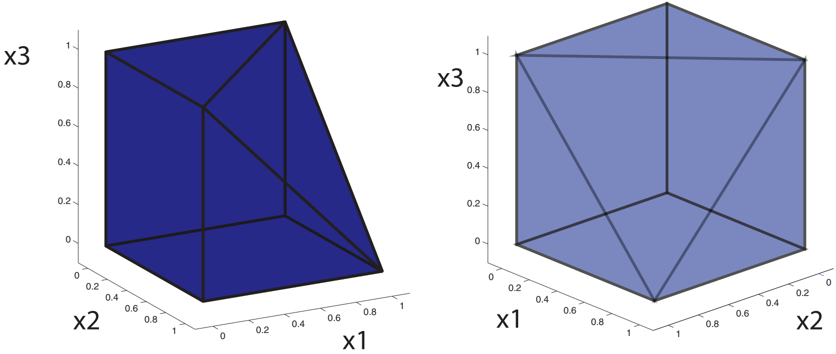
- The set of three edges is dependent, and has rank 2.

Matroid Polyhedron in 3D

Two view of P_r^+ associated with a matroid $(\{e_1, e_2, e_3\}, \{\emptyset, \{e_1\}, \{e_2\}, \{e_3\}, \{e_1, e_2\}, \{e_1, e_3\}, \{e_2, e_3\}\})$.



Matroid Polyhedron in 3D

P_r^+ associated with the "free" matroid in 3D.

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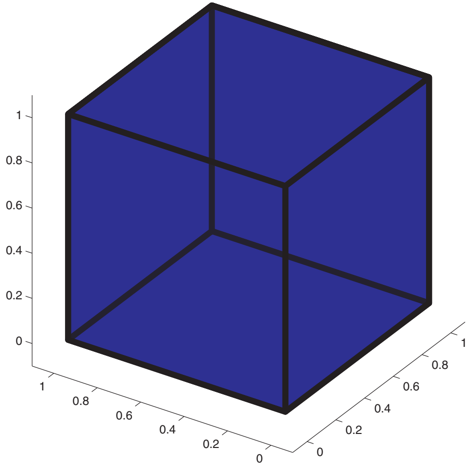

Another Polytope in 3D

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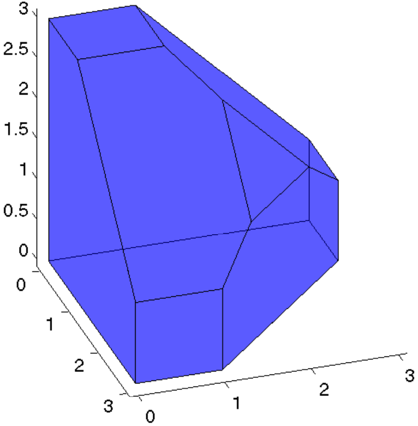

Matroid Independence Polyhedron

- So recall from a moment ago, that we have that

$$\begin{aligned} P_{\text{ind. set}} &= \text{conv}\left\{\cup_{I \in \mathcal{I}}\{\mathbf{1}_I\}\right\} \\ &\subseteq P_r^+ = \left\{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r(A), \forall A \subseteq E\right\} \end{aligned} \tag{9.35}$$

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- In fact, the two polyhedra are identical (and thus both are polytopes).
- We'll show this in the next few theorems.

Maximum weight independent set via greedy weighted rank

Theorem 9.4.1

Let $M = (V, \mathcal{I})$ be a matroid, with rank function r, then for any weight function $w \in \mathbb{R}_+^V$, there exists a chain of sets $U_1 \subset U_2 \subset \cdots \subset U_n \subseteq V$ such that

$$\max \{w(I) | I \in \mathcal{I}\} = \sum_{i=1}^{n} \lambda_i r(U_i) \tag{9.36}$$

where $\lambda_i \geq 0$ satisfy

$$w = \sum_{i=1}^{n} \lambda_i \mathbf{1}_{U_i} \tag{9.37}$$

Maximum weight independent set via weighted rank

Proof.

- Firstly, note that for any such $w \in \mathbb{R}^E$, we have

$$\begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} = (w_1 - w_2)\begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + (w_2 - w_3)\begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \cdots + (w_{n-1} - w_n)\begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \end{pmatrix} + (w_n)\begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{pmatrix} \tag{9.38}$$

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- If we can take w in decreasing order ($w_1 \geq w_2 \geq \cdots \geq w_n$), then each coefficient of the vectors is non-negative (except possibly the last one, w_n).

...

Maximum weight independent set via weighted rank

Proof.

- Now, again assuming $w \in \mathbb{R}_+^E$, order the elements of V non-increasing by w so $(v_1, v_2, \ldots, v_n)$ such that $w(v_1) \geq w(v_2) \geq \cdots \geq w(v_n)$

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- Define the sets U_i based on this order as follows, for $i = 0, \dots, n$

$$U_i \stackrel{\text{def}}{=} \{v_1, v_2, \dots, v_i\} \tag{9.39}$$

Note that $U_0 = \emptyset$ and

$$\mathbf{1}_{U_0} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \mathbf{1}_{U_1} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \dots, \mathbf{1}_{U_\ell} = \begin{pmatrix} \left.\begin{matrix} 1 \\ 1 \\ \vdots \\ 1 \end{matrix}\right\} \ell\times \\ \left.\begin{matrix} 0 \\ 0 \\ \vdots \\ 0 \end{matrix}\right\} (n-\ell)\times \end{pmatrix}, \text{ etc.}$$

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- Define the set I as those elements where the rank increases, i.e.:

$$I \stackrel{\text{def}}{=} \{v_i | r(U_i) > r(U_{i-1})\}. \tag{9.40}$$

Hence, given an i with $v_i \notin I$, $r(U_i) = r(U_{i-1})$.

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- Therefore, I is the output of the greedy algorithm for $\max \{w(I) | I \in \mathcal{I}\}$. *since items v_i are ordered decreasing by $w(v_i)$, and we only choose the ones that increase the rank, which means they don't violate independence.*

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- Therefore, I is the output of the greedy algorithm for $\max\{w(I) | I \in \mathcal{I}\}$.
- And therefore, I is a maximum weight independent set (can even be a base, actually).

...

Maximum weight independent set via weighted rank

Proof.

- Now, we define λ_i as follows

$$0 \leq \lambda_i \stackrel{\text{def}}{=} w(v_i) - w(v_{i+1}) \text{ for } i = 1, \dots, n-1 \tag{9.41}$$

$$\lambda_n \stackrel{\text{def}}{=} w(v_n) \tag{9.42}$$

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- Since we ordered $v_1, v_2, \dots$ non-increasing by w, for all i, and since $w \in \mathbb{R}_+^E$, we have $\lambda_i \geq 0$

□

Linear Program LP

Consider the linear programming primal problem

$$\begin{aligned} \text{maximize} \quad & w^\intercal x \\ \text{subject to} \quad & x_v \geq 0 && (v \in V) \\ & x(U) \leq r(U) && (\forall U \subseteq V) \end{aligned} \tag{9.45}$$

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And its convex dual (note $y \in \mathbb{R}_+^{2^n}$, y_U is a scalar element within this exponentially big vector):

$$\begin{aligned} \text{minimize} \quad & \textstyle\sum_{U \subseteq V} y_U r(U), \\ \text{subject to} \quad & y_U \geq 0 \qquad (\forall U \subseteq V) \\ & \textstyle\sum_{U \subseteq V} y_U \mathbf{1}_U \geq w \end{aligned} \tag{9.46}$$

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Thanks to strong duality, the solutions to these are equal to each other.

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$$\max w^\intercal x \text{ such that } x \in P_r^+ \tag{9.48}$$

where, again, $P_r^+ = \left\{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r(A), \forall A \subseteq E\right\}$.

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- Therefore, since $P_{\text{ind. set}} \subseteq P_r^+$, the above problem can only have a larger solution. I.e.,

$$\max w^\intercal x \text{ s.t. } x \in P_{\text{ind. set}} \leq \max w^\intercal x \text{ s.t. } x \in P_r^+. \tag{9.49}$$

Polytope equivalence

- Hence, we have the following relations:

$$\max\left\{w(I) : I \in \mathcal{I}\right\} \leq \max\left\{w^\intercal x : x \in P_{\text{ind. set}}\right\} \tag{9.50}$$

$$\leq \max\left\{w^\intercal x : x \in P_r^+\right\} \tag{9.51}$$

$$\stackrel{\text{def}}{=} \alpha_{\text{min}} = \min\left\{\sum_{U \subseteq V} y_U r(U) : \forall U, y_U \geq 0; \sum_{U \subseteq V} y_U \mathbf{1}_U \geq w\right\} \tag{9.52}$$

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for the chain of U_i's and $\lambda_i \geq 0$ that satisfies $w = \sum_{i=1}^n \lambda_i \mathbf{1}_{U_i}$ (i.e., the r.h.s. of Eq. 9.53 is feasible w.r.t. the dual LP).

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- Therefore, we also have $\max\{w(I) : I \in \mathcal{I}\} \leq \alpha_{\text{min}}$ and

$$\max\{w(I) : I \in \mathcal{I}\} = \sum_{i=1}^{n} \lambda_i r(U_i) \geq \alpha_{\text{min}} \tag{9.54}$$

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- Therefore, all the inequalities above are equalities.
- And since $w \in \mathbb{R}_+^E$ is an arbitrary direction into the positive orthant, we see that $P_r^+ = P_{\text{ind. set}}$

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- That is, we have just proven:

Theorem 9.4.2

$$P_r^+ = P_{\textit{ind. set}} \tag{9.55}$$

Polytope Equivalence (Summarizing the above)

- For each $I \in \mathcal{I}$ of a matroid $M = (E, \mathcal{I})$, we can form the incidence vector $\mathbf{1}_I$.

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- Now take the rank function r of M, and define the following polytope:

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Theorem 9.4.3

$$P_r^+ = P_{\textit{ind. set}} \tag{9.58}$$

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Theorem 9.4.4

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Theorem 9.4.4

The LP problem $\max\{w^\intercal x : x \in P_r^+\}$ can be solved exactly using the greedy algorithm.

Note that this LP problem has an exponential number of constraints (since P_r^+ is described as the intersection of an exponential number of half spaces).

Greedy solves a linear programming problem

- So we can describe the independence polytope of a matroid using the set of inequalities (an exponential number of them).
- In fact, considering equations starting at Eq 9.50, the LP problem with exponential number of constraints $\max\{w^\intercal x : x \in P_r^+\}$ is identical to the maximum weight independent set problem in a matroid, and since greedy solves the latter problem exactly, we have also proven:

Theorem 9.4.4

The LP problem $\max\{w^\intercal x : x \in P_r^+\}$ *can be solved exactly using the greedy algorithm.*

Note that this LP problem has an exponential number of constraints (since P_r^+ is described as the intersection of an exponential number of half spaces).

- This means that if LP problems have certain structure, they can be solved much easier than immediately implied by the equations.

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- By essentially the same argument as above (Exercise:), we can shown that the convex hull of the incidence vectors of the bases of a matroid is a polytope that can be described by Eq. 9.59- 9.61 above.
- What does this look like?

Spanning set polytope

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- Consider convex hull of incidence vectors of spanning sets of a matroid M, and call this $P_{\text{spanning}}(M)$.

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Theorem 9.4.5

The spanning set polytope is determined by the following equations:

$$0 \leq x_e \leq 1 \qquad \text{for } e \in E \tag{9.62}$$

$$x(A) \geq r(E) - r(E \setminus A) \qquad \text{for } A \subseteq E \tag{9.63}$$

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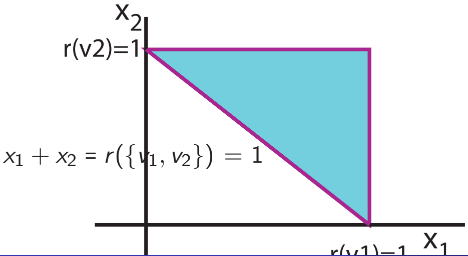
- Example of spanning set polytope in 2D.



Spanning set polytope

Proof.

- Recall that any A is spanning in M iff $E \setminus A$ is independent in M^* (the dual matroid).

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Spanning set polytope

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- Recall that any A is spanning in M iff $E \setminus A$ is independent in M^* (the dual matroid).
- For any $x \in \mathbb{R}^E$, we have that

$$x \in P_{\text{spanning}}(M) \Leftrightarrow 1 - x \in P_{\text{ind. set}}(M^*) \tag{9.64}$$

as we show next ...

...

Spanning set polytope

... proof continued.

- This follows since if $x \in P_{\text{spanning}}(M)$, we can represent x as a convex combination:

$$x = \sum_i \lambda_i \mathbf{1}_{A_i} \tag{9.65}$$

where A_i is spanning in M.

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Spanning set polytope

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- Consider

$$\mathbf{1} - x = \mathbf{1}_E - x = \mathbf{1}_E - \sum_i \lambda_i \mathbf{1}_{A_i} = \sum_i \lambda_i \mathbf{1}_{E \setminus A_i}, \tag{9.66}$$

which follows since $\sum_i \lambda_i \mathbf{1} = \mathbf{1}_E$, so $\mathbf{1} - x$ is a convex combination of independent sets in M^* and so $\mathbf{1} - x \in P_{\text{ind. set}}(M^*)$.

. . .

Spanning set polytope

. . . proof continued.

- which means, from the definition of $P_{\text{ind. set}}(M^*)$, that

$$\mathbf{1} - x \geq 0 \tag{9.67}$$

$$\mathbf{1}_A - x(A) = |A| - x(A) \leq r_{M^*}(A) \text{ for } A \subseteq E \tag{9.68}$$

And we know the dual rank function is

$$r_{M^*}(A) = |A| + r_M(E \setminus A) - r_M(E) \tag{9.69}$$

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- giving

$$x(A) \geq r_M(E) - r_M(E \setminus A) \text{ for all } A \subseteq E \tag{9.70}$$

□

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Matroids

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- We've been discussing results about matroids (independence polytope, etc.).
- By now, it is clear that matroid rank functions are special cases of submodular functions. We ultimately will be reviewing submodular function minimization procedures, but in some cases it it worth showing a result for a general submodular function first.
- Henceforth, we will skip between submodular functions and matroids, each lecture talking less about matroids specifically and taking more about submodular functions more generally …

Maximal points in a set

- Regarding sets, a subset X of S is a maximal subset of S possessing a given property $\mathfrak{P}$ if X possesses property $\mathfrak{P}$ and no set properly containing X (i.e., any $X' \supset X$ with $X' \setminus X \subseteq V \setminus X$) possesses $\mathfrak{P}$.

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- Given any compact (essentially closed & bounded) set $P \subseteq \mathbb{R}^E$, we say that a vector x is maximal within P if it is the case that for any $\epsilon > 0$, and for all directions $e \in E$, we have that

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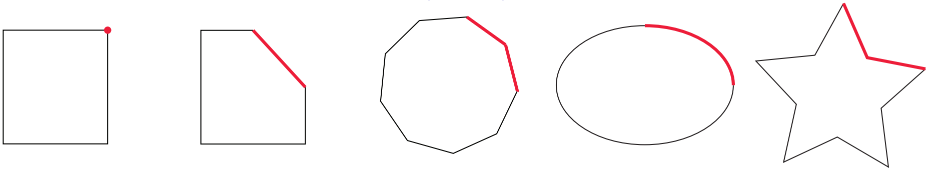
- Examples of maximal regions (in red)



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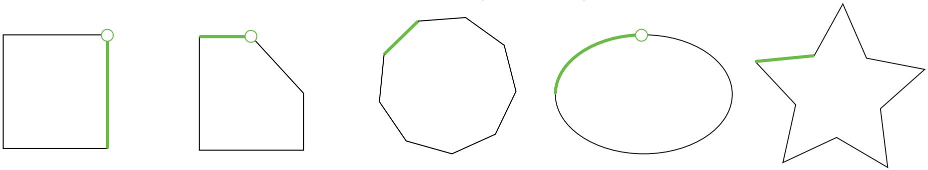
- Examples of non-maximal regions (in green)



Review from Lecture 6

- The next slide comes from Lecture 6.

Matroids, independent sets, and bases

- Independent sets: Given a matroid $M = (E, \mathcal{I})$, a subset $A \subseteq E$ is called independent if $A \in \mathcal{I}$ and otherwise A is called dependent.
- A base of $U \subseteq E$: For $U \subseteq E$, a subset $B \subseteq U$ is called a base of U if B is inclusionwise maximally independent subset of U. That is, $B \in \mathcal{I}$ and there is no $Z \in \mathcal{I}$ with $B \subset Z \subseteq U$.
- A base of a matroid: If $U = E$, then a "base of E" is just called a base of the matroid M (this corresponds to a basis in a linear space, or a spanning forest in a graph, or a spanning tree in a connected graph).

P-basis of x given compact set $P \subseteq \mathbb{R}_+^E$

Definition 9.5.1 (subvector)

y is a subvector of x if $y \leq x$ (meaning $y(e) \leq x(e)$ for all $e \in E$).

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Here, by y being "maximal", we mean that there exists no $z > y$ (more precisely, no $z \geq y + \epsilon \mathbf{1}_e$ for some $e \in E$ and $\epsilon > 0$) having the properties of y (the properties of y being: in P, and a subvector of x).

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1. $y \leq x$ (y is a subvector of x); and
2. $y \in P$ and $y + \epsilon \mathbf{1}_e \notin P$ for all $e \in E$ where $y(e) < x(e)$ and $\forall \epsilon > 0$ (y is maximal P-contained).

A vector form of rank

- Recall the definition of rank from a matroid $M = (E, \mathcal{I})$.

$$\text{rank}(A) = \max \{|I| : I \subseteq A, I \in \mathcal{I}\} = \max_{I \in \mathcal{I}} |A \cap I| \tag{9.72}$$

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$$\text{rank}(x) = \max (y(E) : y \leq x, y \in P) = \max_{y \in P} (x \wedge y)(E) \tag{9.73}$$

where $y \leq x$ is componentwise inequality ($y_i \leq x_i, \forall i$), and where $(x \wedge y) \in \mathbb{R}_+^E$ has $(x \wedge y)(i) = \min(x(i), y(i))$.

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- If $x \in P$, then $\text{rank}(x) = x(E)$ (x is its own unique self P-basis).
- If $x_{\text{min}} = \min_{x \in P} x(E)$, and $x \leq x_{\text{min}}$ what then? $-\infty$?

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- If $x_{\min} = \min_{x \in P} x(E)$, and $x \leq x_{\min}$ what then? $-\infty$?
- In general, might be hard to compute and/or have ill-defined properties. Next, we look at an object that restrains and cultivates this form of rank.

Polymatroidal polyhedron (or a "polymatroid")

Definition 9.5.3 (polymatroid)

A polymatroid is a compact set $P \subseteq \mathbb{R}_+^E$ satisfying

1. $0 \in P$
2. If $y \leq x \in P$ then $y \in P$ (called down monotone).
3. For every $x \in \mathbb{R}_+^E$, any maximal vector $y \in P$ with $y \leq x$ (i.e., any P-basis of x), has the same component sum $y(E)$

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- Condition 3 restated: That is for any two distinct maximal vectors $y^1, y^2 \in P$, with $y^1 \leq x$ & $y^2 \leq x$, with $y^1 \neq y^2$, we must have $y^1(E) = y^2(E)$.

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- Condition 3 restated (again): For every vector $x \in \mathbb{R}_+^E$, every maximal independent (i.e., $\in P$) subvector y of x has the same component sum $y(E) = \text{rank}(x)$.

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- Condition 3 restated (yet again): All P-bases of x have the same component sum.

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- Vectors within P (i.e., any $y \in P$) are called independent, and any vector outside of P is called dependent.
- Since all P-bases of x have the same component sum, if $\mathcal{B}_x$ is the set of P-bases of x, than $\text{rank}(x) = y(E)$ for any $y \in \mathcal{B}_x$.

Matroid and Polymatroid: side-by-side

A Matroid is:

A Polymatroid is:

Matroid and Polymatroid: side-by-side

A Matroid is:

1. a set system $(E, \mathcal{I})$

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1. a compact set $P \subseteq \mathbb{R}_+^E$

Matroid and Polymatroid: side-by-side

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Matroid and Polymatroid: side-by-side

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2. empty-set containing $\emptyset \in \mathcal{I}$
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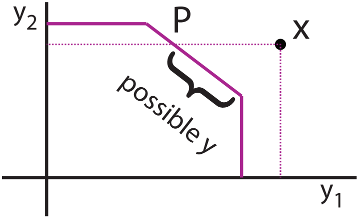
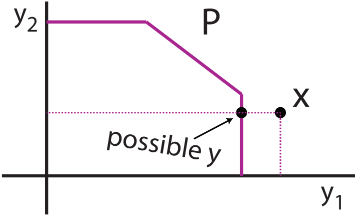
4. any maximal set I in $\mathcal{I}$, bounded by another set A, has the same matroid rank (any maximal independent subset $I \subseteq A$ has same size $|I|$).

A Polymatroid is:

1. a compact set $P \subseteq \mathbb{R}_+^E$
2. zero containing, $\mathbf{0} \in P$
3. down monotone, $0 \leq y \leq x \in P \Rightarrow y \in P$
4. any maximal vector y in P, bounded by another vector x, has the same vector rank (any maximal independent subvector $y \leq x$ has same sum $y(E)$).

Polymatroidal polyhedron (or a "polymatroid")





Left: $\exists$ multiple maximal $y \leq x$ Right: $\exists$ only one maximal $y \leq x$,

- Polymatroid condition here: $\forall$ maximal $y \in P$, with $y \leq x$ (which here means $y_1 \leq x_1$ and $y_2 \leq x_2$), we just have $y(E) = y_1 + y_2 =$ const.

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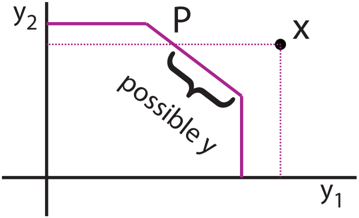

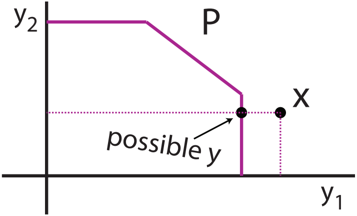

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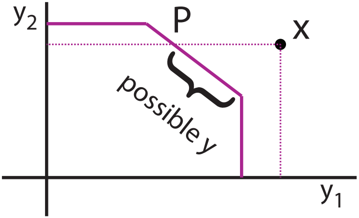

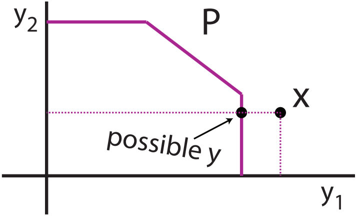

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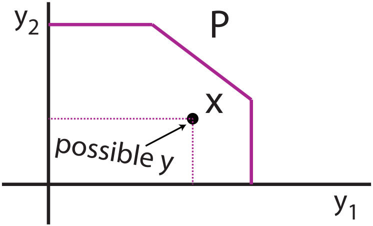
- On the left, we see there are multiple possible maximal $y \in P$ such that $y \leq x$. Each such y must have the same value $y(E)$.
- On the right, there is only one maximal $y \in P$. Since there is only one, the condition on the same value of $y(E), \forall y$ is vacuous.

Polymatroidal polyhedron (or a "polymatroid")



∃ only one maximal $y \leq x$.

- If $x \in P$ already, then x is its own P-basis, i.e., it is a self P-basis.

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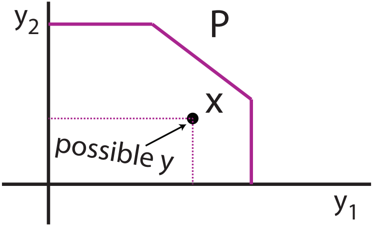
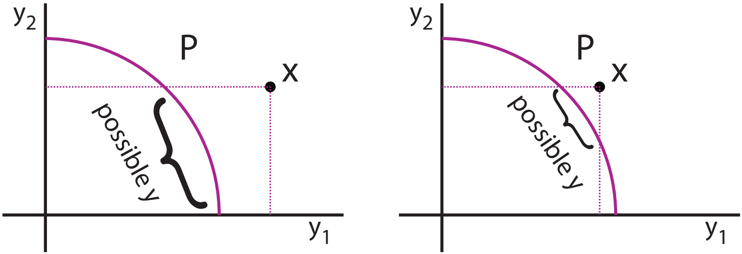


∃ only one maximal $y \leq x$.

- If $x \in P$ already, then x is its own P-basis, i.e., it is a self P-basis.
- In a matroid, a base of A is the maximally contained independent set. If A is already independent, then A is a self-base of A (as we saw in previous Lectures)

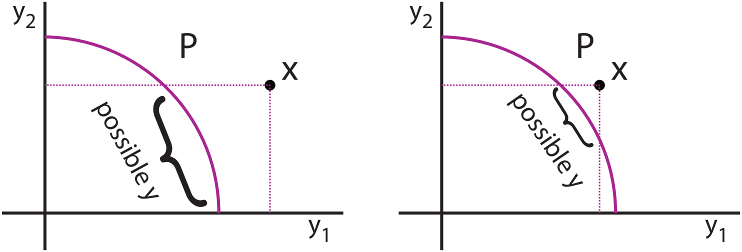
Polymatroid as well?



Left and right: $\exists$ multiple maximal $y \leq x$ as indicated.

- On the left, we see there are multiple possible maximal such $y \in P$ that are $y \leq x$. Each such y must have the same value $y(E)$, but since the equation for the curve is $y_1^2 + y_2^2 =$ const. $\neq y_1 + y_2$, we see this is not a polymatroid.

Polymatroid as well? no



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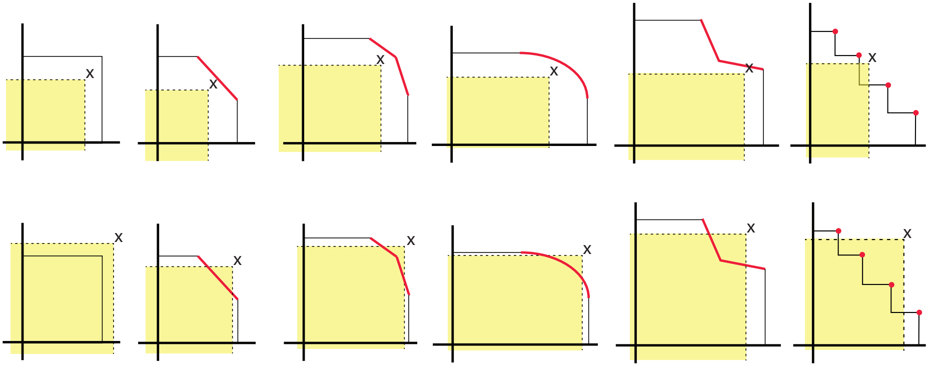
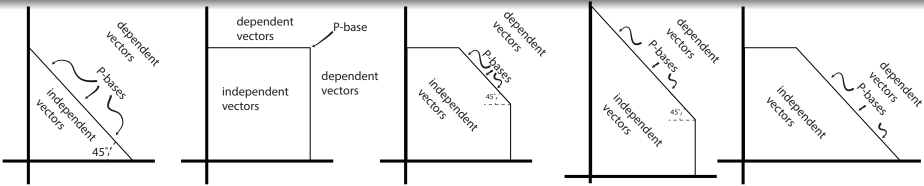
- On the right, we have a similar situation, just the set of potential values that must have the $y(E)$ condition changes, but the values of course are still not constant.

Other examples: Polymatroid or not?



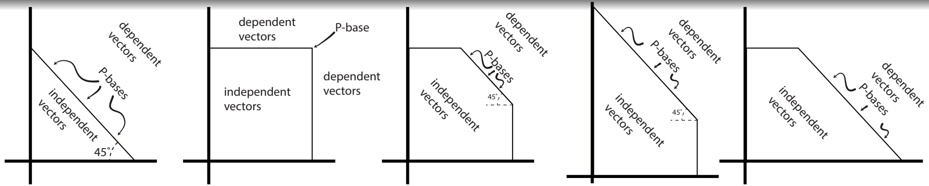
Some possible polymatroid forms in 2D



It appears that we have five possible forms of polymatroid in 2D, when neither of the elements $\{v_1, v_2\}$ are self-dependent.

1. On the left: full dependence between v_1 and v_2

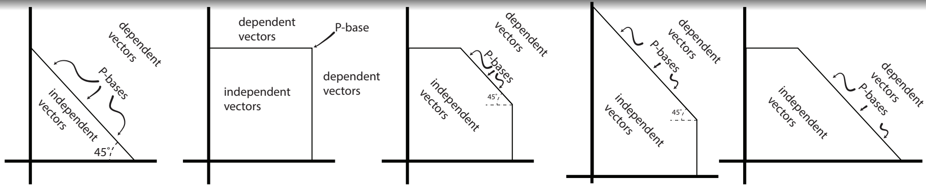
Some possible polymatroid forms in 2D



It appears that we have five possible forms of polymatroid in 2D, when neither of the elements $\{v_1, v_2\}$ are self-dependent.

1. On the left: full dependence between v_1 and v_2
2. Next: full independence between v_1 and v_2

Some possible polymatroid forms in 2D



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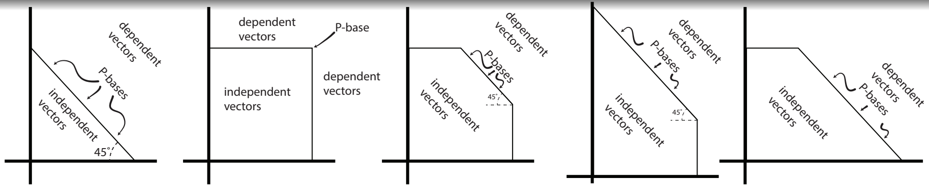
1. On the left: full dependence between v_1 and v_2
2. Next: full independence between v_1 and v_2
3. Next: partial independence between v_1 and v_2

Some possible polymatroid forms in 2D



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4. Right two: other forms of partial independence between v_1 and v_2

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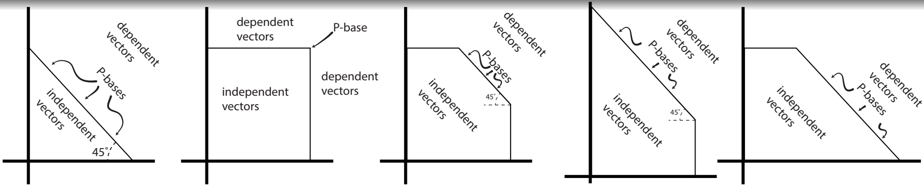

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- The P-bases (or single P-base in the middle case) are as indicated.

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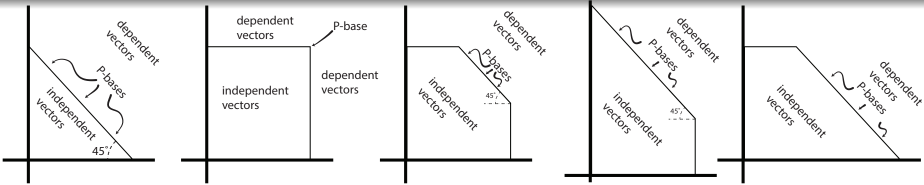

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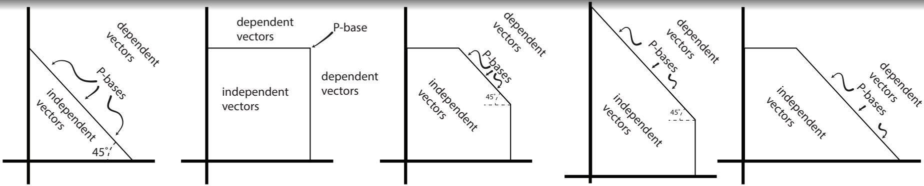

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- The P-bases (or single P-base in the middle case) are as indicated.
- Independent vectors are those within or on the boundary of the polytope. Dependent vectors are exterior to the polytope.
- The set of P-bases for a polytope is called the base polytope.

Polymatroidal polyhedron (or a "polymatroid")

- Note that if x contains any zeros (i.e., suppose that $x \in \mathbb{R}_+^E$ has $E \setminus S$ s.t. $x(E \setminus S) = 0$, so S indicates the non-zero elements, or $S = \text{supp}(x)$), then this also forces $y(E \setminus S) = 0$, so that $y(E) = y(S)$. This is true either for $x \in P$ or $x \notin P$.

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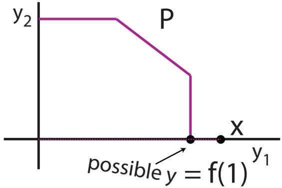
- Therefore, in this case, it is the non-zero elements of x, corresponding to elements S (i.e., the support $\text{supp}(x)$ of x), determine the common component sum.
- For the case of either $x \notin P$ or right at the boundary of P, we might give a "name" to this component sum, lets say $f(S)$ for any given set S of non-zero elements of x. We could name rank$(\frac{1}{\epsilon}\mathbf{1}_S) \triangleq f(S)$ for ϵ small enough. What kind of function might f be?



Polymatroid function and its polyhedron.

Definition 9.5.4

A polymatroid function is a real-valued function f defined on subsets of E which is normalized, non-decreasing, and submodular. That is we have

1. $f(\emptyset) = 0$ (normalized)
2. $f(A) \leq f(B)$ for any $A \subseteq B \subseteq E$ (monotone non-decreasing)
3. $f(A \cup B) + f(A \cap B) \leq f(A) + f(B)$ for any $A, B \subseteq E$ (submodular)

We can define the polyhedron P_f^+ associated with a polymatroid function as follows

$$P_f^+ = \left\{ y \in \mathbb{R}_+^E : y(A) \leq f(A) \text{ for all } A \subseteq E \right\} \quad (9.74)$$

$$= \left\{ y \in \mathbb{R}^E : y \geq 0, y(A) \leq f(A) \text{ for all } A \subseteq E \right\} \quad (9.75)$$

Associated polyhedron with a polymatroid function

$$P_f^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq f(A), \forall A \subseteq E\} \tag{9.76}$$

- Consider this in three dimensions. We have equations of the form:

$$x_1 \geq 0 \text{ and } x_2 \geq 0 \text{ and } x_3 \geq 0 \tag{9.77}$$
$$x_1 \leq f(\{v_1\}) \tag{9.78}$$
$$x_2 \leq f(\{v_2\}) \tag{9.79}$$
$$x_3 \leq f(\{v_3\}) \tag{9.80}$$
$$x_1 + x_2 \leq f(\{v_1, v_2\}) \tag{9.81}$$
$$x_2 + x_3 \leq f(\{v_2, v_3\}) \tag{9.82}$$
$$x_1 + x_3 \leq f(\{v_1, v_3\}) \tag{9.83}$$
$$x_1 + x_2 + x_3 \leq f(\{v_1, v_2, v_3\}) \tag{9.84}$$

Associated polyhedron with a polymatroid function

- Consider the asymmetric graph cut function on the simple chain graph $v_1 - v_2 - v_3$. That is, $f(S) = |\{(v,s) \in E(G) : v \in V, s \in S\}|$ is count of any edges within S or between S and $V \setminus S$, so that $\delta(S) = f(S) + f(V \setminus S) - f(V)$ is the standard graph cut.

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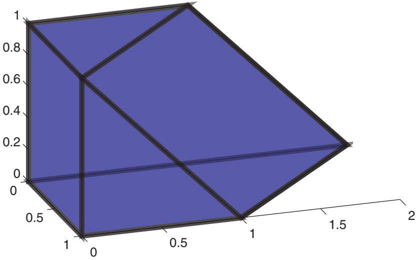
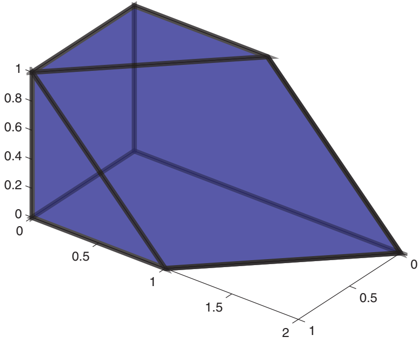
- Observe: P_f^+ (at two views):





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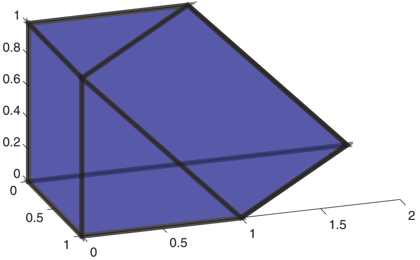

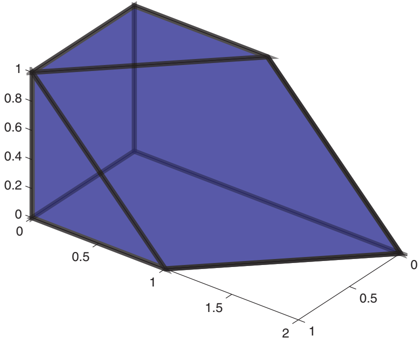

- which axis is which?

Associated polyhedron with a polymatroid function

- Consider: $f(\emptyset) = 0$, $f(\{v_1\}) = 1.5$, $f(\{v_2\}) = 2$, $f(\{v_1, v_2\}) = 2.5$, $f(\{v_3\}) = 3$, $f(\{v_3, v_1\}) = 3.5$, $f(\{v_3, v_2\}) = 4$, $f(\{v_3, v_2, v_1\}) = 4.3$.

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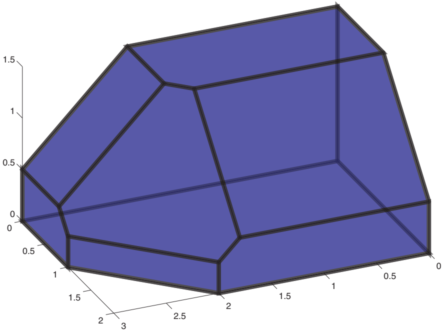

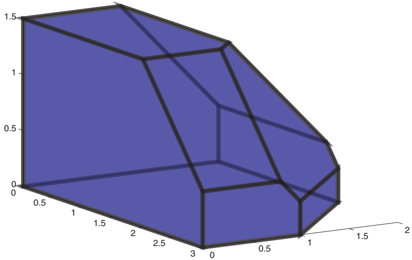

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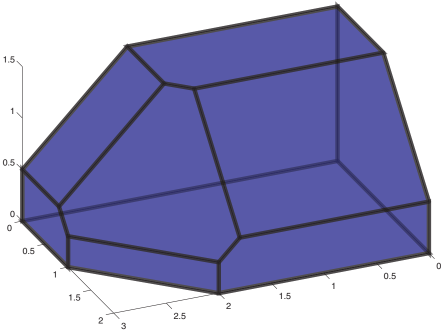

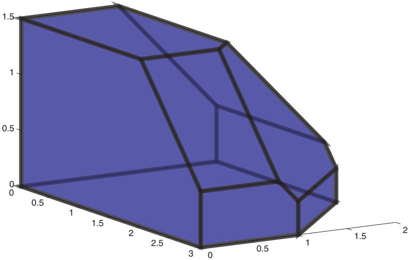

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Associated polyhedron with a polymatroid function

- Consider modular function $w : V \to \mathbb{R}_+$ as $w = (1, 1.5, 2)^\intercal$, and then the submodular function $f(S) = \sqrt{w(S)}$.

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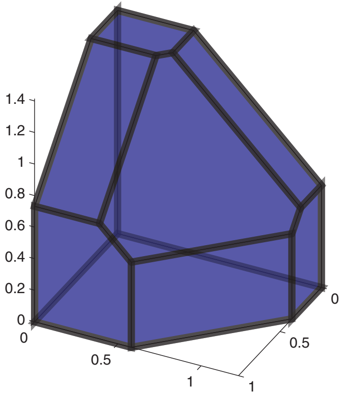

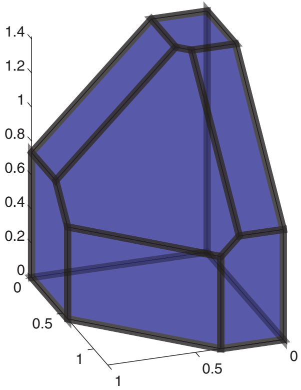

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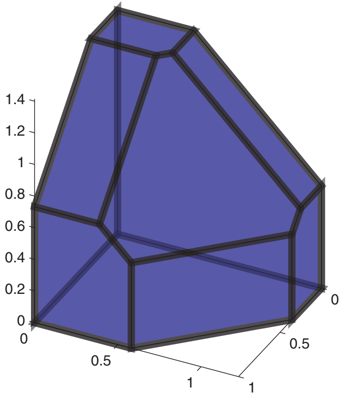

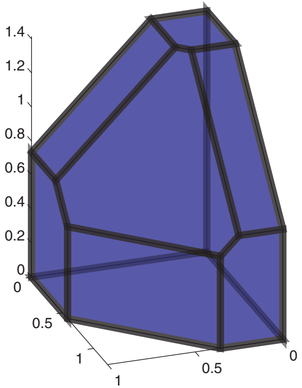

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Associated polytope with a non-submodular function

- Consider function on integers: $g(0) = 0$, $g(1) = 3$, $g(2) = 4$, and $g(3) = 5.5$.

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Associated polytope with a non-submodular function

- Consider function on integers: $g(0) = 0$, $g(1) = 3$, $g(2) = 4$, and $g(3) = 5.5$. Is $f(S) = g(|S|)$ submodular? $f(S) = g(|S|)$ is not submodular since $f(\{e_1, e_3\}) + f(\{e_1, e_2\}) = 4 + 4 = 8$ but $f(\{e_1, e_2, e_3\}) + f(\{e_1\}) = 5.5 + 3 = 8.5$.

Associated polytope with a non-submodular function

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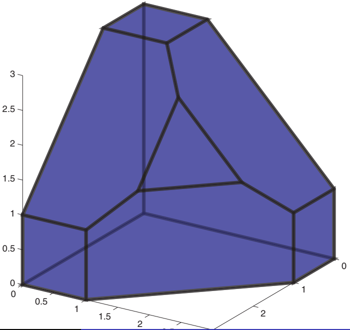
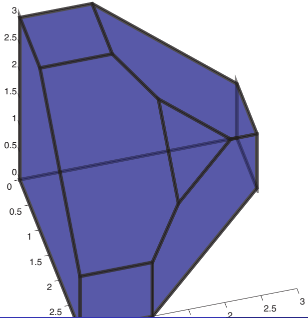
- Observe: P_f^+ (at two views), maximal independent subvectors not constant rank, hence not a polymatroid.





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- In the next theorem, we show that any P_f^+-basis has the same component sum, when f is a polymatroid function, and P_f^+ satisfies the other properties so that P_f^+ is a polymatroid.